

The CCB2004, MPC2004 and MS2005 User's Guide

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1. Clock and Control Board CCB2004

This User's Guide should be used together with the CCB2004 Specification [1] and the TTCrx Reference Manual [2]. The TTCrx ASIC can be programmed from the TTC source (four main registers, write only, see Section 1.1) and over I²C serial bus using VME accesses in the CCB2004 address space (write and read, see Section 1.2). JTAG access to TTCrx ASIC has not been implemented on the CCB2004 board.

1.1 Initialization

After power cycling make sure that the four green LEDs on the front panel indicating active powers as well as "DONE" LED (FPGA was successfully configured from its EPROM) are "on". When optical connection between the TTCrq and the source of the TTC clock and commands (TTCvi [3] or TTCci modules) is established, the "TTCRDY" and "QLOCK" LEDs of the front panel of the CCB2004 must be "on". They just repeat the state of the respective LEDs on TTCrq mezzanine board (also visible through the CCB2004 front panel). If an optical fiber is plugged in from both sides, and both source and destination operate properly, the connection will be established automatically after power cycling. Make sure the "CLK40" LED on the front panel is blinking (~7Hz). Then:

1. Program **CSRA1** (write data = **Fh** for the "Discrete Logic" mode, write data = **Eh** for the "FPGA" mode). The only source of L1A for all boards in the crate in a "Discrete Logic" mode will be the TTCrx ASIC.
2. Program **CSRB1**. CSRB1[0]=0 for the "FPGA External" and CSRB1[0]=1 for the "FPGA Internal" modes. Use appropriate values to mask/unmask the L1A sources. **Note: It's important to program the CSRB1 even if the CCB2004 is in "Discrete Logic" mode to be able to use the L1A front panel output correctly.**
3. Write **any data** into **CSRA3** (generate "**Soft_Reset**" for the FPGA). "Soft_Reset" command enables propagation of selected L1A and "external trigger" signals to custom backplane, disables 32-bit L1A counter and resets the CSRB11[10..8] bits. It does not affect the content of all other CSRB[1..18] registers. A "Hard_Reset" command is intended for recovery from possible Single Event Upsets in the LHC environment. It is not necessary to send a "Hard_Reset" during initialization.

4. Write appropriate **delay value** into **CSRB5**. It affects the delay of the L1A signal to custom backplane in the “FPGA” mode and delay of the L1A to the front panel (in both “FPGA” and “Discrete Logic” modes).
5. (Optional) Read **CSRB17** to verify the date of the firmware revision.

All the CCB2004 boards are equipped with the TTCrq mezzanines [2]. The jumpers on TTCrq board (see Chapter 8 in [2]) select the unique 14-bit ID address of the mezzanine that is required for the individually addressed TTC commands as well as for the I²C accesses to TTCrx. This address must be latched into the ASIC during initialization at the rising edge of the Reset_b signal. To do this the following steps are needed:

6. Send “**Reset TTCrx ASIC**” command (write **any data** to **base+5C** address).
7. Wait at least 60 microseconds.
8. Read **CSRB18**. CSRB18[15..8]=00000001 for all the TTCrq mezzanines intended for the CSC system. Bits CSRB18[7..0] are unique for each CCB2004 and equal to a serial number (1..99) of the main CCB2004 board. This number is labeled on the front panel and on the main board as well. Out of these 8 bits, the lowest 6 bits are used to calculate the base I²C address, see Chapter 7 in [2]. The 14-bit ID address can also be read back and verified directly from the TTCrx ASIC over I²C bus, registers 16-18, see Chapter 3 in [2].
9. Read **CSRA2 and CSRA3**. Make sure CSRA3[13..12] = 1 and CSRA3[14] = 0. Check the other bits in CSRA2 and CSRA3 to verify that all the installed peripheral boards were configured successfully.
10. (Optional) Read the unique 64-bit board ID (see Section 1.3).

Initialization of the TTCrx ASIC requires the following steps (examples below are referred to TTCvi module. The same procedures can be performed over I²C bus as well).

11. Write **fine delay values “xx”** into “**Fine Delay**” register 1 in the TTCrx ASIC if needed (see Appendix A in [2] for more details):
 - write data = **8000h** into **base+C0** address on TTCvi board
 - write data = **xxh** into **base+C2** address on TTCvi board
12. Write **coarse delay values “x”** into “**Coarse Delay**” register in the TTCrx ASIC (note that bits [3:0] must be equal to bits[7:4] for correct command decoding):
 - write data = **8000h** into **base+C0** address on TTCvi board
 - write data = **2xxh** into **base+C2** address on TTCvi board.
13. Program **Control Register** in the TTCrx ASIC:
 - write data = **8000h** into **base+C0** address on TTCvi board
 - write data = **3b3h** into **base+C2** address on TTCvi board (enable parallel output bus of the TTCrx, enable bunch counter and event counter operation, so the Trigger mode “11” is selected, see Chapter 6 in [2], use Clock40Des1 for the synchronization of the BrestStr2 and the broadcast command bits Brcst[7:6]).

14. **Clear the discrete logic decoder** on CCB2004 board with the long-format broadcast command = **0**:

- write data = **8001h** into **base+C0** register on TTCvi board
- write data = **0** into **base+C2** address on TTCvi board.

1.2. I²C Interface

The I²C is a 2-wire interface used on CCB2004 board for communications with the TTCrx ASIC residing on a TTCrq mezzanine board. General description of the I²C protocol can be found in [4], while the TTCrx specific implementation of the I²C functions can be found in Chapter 7 of the TTCrx Reference Manual [2]. The I²C interface provides access to all the internal registers of the TTCrx ASIC from the VME through the CSR1[4..1] bits, see Section 6 of the CCB2004 specification [1]. The I²C access is possible in any (“Discrete Logic” or “FPGA”) mode of the CCB2004 operation.

Note that the correct operation of the I²C bus requires the TTCrx to be locked to the TTC signal (“TTC_Ready”=1), see Chapter 7 in [2].

Each TTCrq board has a unique 14-bit ID number encoded with the soldered resistors, as shown on Fig.9 [2]. A 6-bit portion Dout<5..0> of this 14-bit ID number defines the base I²C address as described in Table 12 [2]. On all production CCB2004 boards this 6-bit address is equal to serial number of the boards which is labeled on its front panel. For example, Dout<5..0>=32h on TTCrq which is installed on CCB2004 #50. This number must be loaded into the TTCrx ASIC at the rising edge of the Reset_b signal. A reset of the TTCrx (by writing any data to base+5Ch address of the CCB2004) should be done only once during CCB2004 initialization. The duration of the reset procedure should be ~60 microseconds (as described in steps 1-3 in Section 1.1. above), so the next operation should be delayed for that period. The following steps are required to perform a write (read) operation after that (this is an example for the “FPGA” mode):

1. Generate **“Start”** condition (“high-to-low” transition on SDA line when SCL is “high”):
 - write data = **Eh** into **CSRA1** (set both SDA and SCL lines “high”, i.e. inactive)
 - write data = **Ah** into **CSRA1** (set SDA “low”)
 - write data = **2** into **CSRA1** (set SCL “low”).

2. **Write 7-bit address of the pointer register** (MSB should be written first, LSB last). This address is calculated as Dout<5..0> * 2. During all write cycled the CSRA1[1] should be “1”. Data is written on “low-to-high” transition of SCL while SDA is valid. To load “1” the following steps are required:
 - write data = **6** into **CSRA1** (set SDA = 1 while SCL=0)
 - write data = **Eh** into **CSRA1** (set SCL = 1)
 - write data = **6** into **CSRA1** (set SCL = 0)
 - write data = **2** into **CSRA1** (release SDA)
 To load “0” the following steps are required:

- write data = **2** into **CSRA1** (set SDA = 0 while SCL=0)
- write data = **Ah** into **CSRA1** (set SCL = 1)
- write data = **2** into **CSRA1** (set SCL = 0, SDA = 0)

Load all 7 bits of the pointer address as described above.

3. Write the **8th bit** called “write” = **0**, as described above.
4. Check the “**acknowledgement**” signal:
 - write data = **4** into **CSRA1** (enable “read” operation, set SDA “high”)
 - write data = **Ch** into **CSRA1** (set SCL “high” while SDA is “high”)
 - read **CSRA1** and make sure the **CSRA1[4]=0** (i.e. the cycle was acknowledged)
 - write data = **4** into **CSRA1** (set SCL “low” while SDA is “high”)
 - write data = **2** into **CSRA1** (disable “read” operation)
5. Write the **8-bit number of the register to be addressed**, MSB first, LSB last, similarly to step 2 above. This could be any TTCrx internal register listed in the Table 3 of [2].
6. Check the “**acknowledgement**” as described in step 4 above.
7. Generate “**stop**” condition (“low-to-high” transition on SDA while SCL is “high”):
 - write data = **2** into **CSRA1** (set SDA = SCL = “low”)
 - write data = **Ah** into **CSRA1** (set SDA “high”)
 - write data = **Eh** into **CSRA1** (set SCL “high”).
8. **Write data to the register selected by the pointer** (or read data; see 8.1.below):
 - generate “**start**” condition
 - write **7-bit address of the data register** as described in step 2. **The address of the data register = address of the pointer + 1**
 - write the **8th bit** called “write” = **0**
 - check the “**acknowledgement**”
 - write **8-bit data into data register**, MSB first, LSB last
 - check the “**acknowledgement**”
 - generate “**stop**” condition.
- 8.1. **Read data from the register selected by the pointer**
 - generate “**start**” condition
 - **write 7-bit address of the data register to read data from** . **The address of the data register = address of the pointer + 1**
 - write the **8th bit =1** (for read operation)
 - check the “**acknowledgement**”
 - **read 8-bit data** (MSB first, LSB last). Each read cycle consists of the following four steps:
 1. write data = **4** to **CSRA1** (enable read, set SDA “high” or inactive)
 2. write data = **Ch** to **CSRA1** (set SCL “high”)
 3. read **CSRA1** and get the expected read value from **CSRA1[4]**
 4. write data = **4** to **CSRA1** (set SCL “low” while SDA is “high”)
 - check the “**no acknowledgement**” state, i.e. read **CSRA1** and verify that the **CSRA1[4]=1**
 - generate “**stop**” condition.

An example of the C++ program to perform I²C accesses to TTCrx ASIC is given in [5].

1.3. 1-Wire Interface

1-Wire is a proprietary Maxim – Dallas Semiconductor interface for communication with the Silicon Serial Number DS2401 chip that consists of a factory-lasered 64-bit ROM that includes a unique 48-bit serial number, an 8-bit CRC, and an 8-bit Family Code (01h). Data is transferred serially via the 1-Wire protocol, read and write least significant bit first. The protocol details and timing diagrams are given in [6]. Access to serial number chip consists of three phases: Initialization, ROM Function Command, and Read Data.

The Initialization sequence consists of a “Reset pulse” transmitted by the master followed by a “Presence pulse” transmitted by the DS2401. The “Presence pulse” lets the bus master know that the DS2401 is on the bus and ready to operate. For the Initialization, the “Reset pulse” should be sent, then CSRB9[2] should be checked, and, when the CSRB9[2]=1, the CSRB9[0] should be read out. If CSRB9[0]=0 at this moment, that means that the “Presence pulse” was sent and the next step can be performed.

The ROM Function Command phase consists of sending a Read ROM command [33h] or [0Fh] to DS2401. The first bit (“Write-one”) should be sent, then CSRB9[4] scanned, and, when CSRB9[4]=1, the next bit of command should be sent. Since all commands are 8-bit long, eight write operations are necessary.

The Read Data phase consists of 64 read cycles. Each cycle starts with sending a “Read pulse”, then CSRB9[3] is scanned, and, when CSRB9[3]=1, the valid data bit should be received from CSRB9[1]. Note the first data bit should be “1” and the next seven bits should be “0” (they represent the Family Code 01h). Bits 49-56 are also “0” and bits 57-64 represent the CRC code.

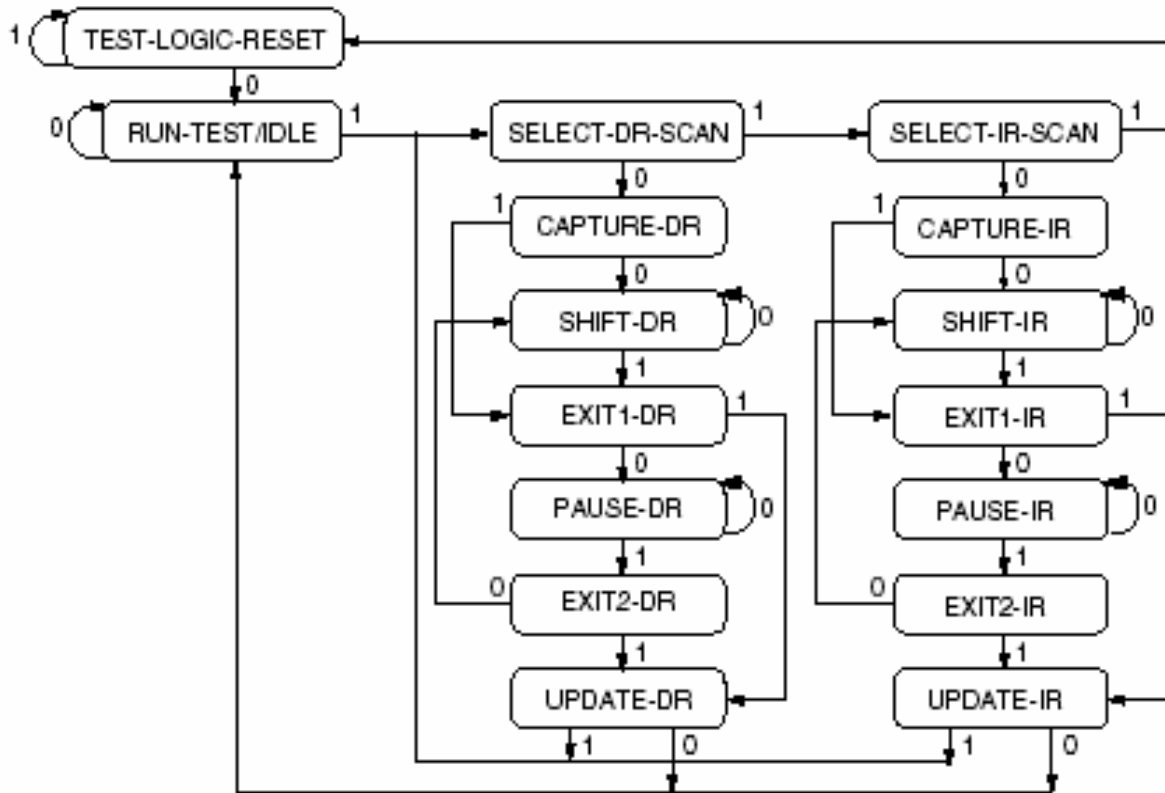
An example of the C++ program to read the DS2401 serial ID can be found in [7].

1.4. JTAG Access to FPGA and EPROM and Firmware Upgrade

One Xilinx XC2V250-4FG456 FPGA and one XC18V02 EPROM are used on CCB2004 board. Both devices can be accessed over JTAG bus. JTAG protocol can be emulated using write and read operations directed to CSRA1[8..5]. The other optional access is possible using Xilinx Parallel Cable IV over the front panel connector. An on-board switch S10-1 defines which of these two options is selected. The EPROM is the 1st device in a JTAG chain, and the FPGA is the 2nd one. Files with the .mcs and .svf extension (produced by Xilinx ISE development system) are needed to reprogram the EPROM with the Xilinx downloading cable and VME path respectively. The most recent version of the downloading file can be found in [8].

Four bits of CSRA1[8..5] (bit 5 for TDI, bit 6 for TMS, bit 7 for TCK, bit 8 for TDO) are used to implement the JTAG protocol. These four Test Access Point (TAP) pins control how data is scanned into the various registers. The state of the TMS pin at a rising edge

of TCK determines the sequence of state transitions. There are two main sequences, one for shifting data into the data register and the other for shifting an instruction into the instruction register (see State Diagram for the TAP Controller on Fig.1). Below is an example of how to read the 32-bit IDCODE code from Xilinx XC18V02 EPROM over JTAG using VME accesses. Datasheet [9] is essential for understanding of the JTAG access to Xilinx EPROM.



NOTE: The value shown adjacent to each state transition in this figure represents the signal present at TMS at the time of a rising edge at TCK.

Figure 1: State Diagram for the TAP Controller

1. Set **Test-Logic-Reset** mode 5 times: repeat 5 times the following sequence:
 - write data = **4Fh** into **CSRA1** (set TMS =1)
 - write data = **CFh** into **CSRA1** (set TCK =1)
 - write data = **4Fh** into **CSRA1** (set TCK = 0)
 - write data = **0Fh** into **CSRA1** (set TMS = 0).
2. Set **Run-Test/Idle** mode:
 - write data = **0Fh** into **CSRA1** (set TMS = TCK = TDI =0)
 - write data = **8Fh** into **CSRA1** (set TCK =1)
 - write data = **0Fh** into **CSRA1** (set TCK =0).
3. Set **Select-DR-Scan** mode:
 - write data = **4Fh** into **CSRA1** (set TMS =1)
 - write data = **CFh** into **CSRA1** (set TCK = 1)
 - write data = **4Fh** into **CSRA1** (set TCK = 0)

- write data = **0Fh** into **CSRA1** (set TMS = 0).
4. Set **Select-IR-Scan** mode:
 - write data = **4Fh** into **CSRA1** (set TMS =1)
 - write data = **CFh** into **CSRA1** (set TCK = 1)
 - write data = **4Fh** into **CSRA1** (set TCK = 0)
 - write data = **0Fh** into **CSRA1** (set TMS = 0).
 5. Set **Capture-IR-Scan** mode:
 - write data = **0Fh** into **CSRA1** (set TMS = TCK = TDI =0)
 - write data = **8Fh** into **CSRA1** (set TCK =1)
 - write data = **0Fh** into **CSRA1** (set TCK =0).
 6. Set **Shift-IR-Scan** mode:
 - write data = **0Fh** into **CSRA1** (set TMS = TCK = TDI =0)
 - write data = **8Fh** into **CSRA1** (set TCK =1)
 - write data = **0Fh** into **CSRA1** (set TCK =0).
 7. Send 6-bit **Bypass** instruction “**111111**” to XC2V250 FPGA. To do this, repeat 6 times the following sequence:
 - write data = **2Fh** into **CSRA1** (set TDI = 1)
 - write data = **AFh** into **CSRA1** (set TCK =1)
 - write data = **2Fh** into **CSRA1** (set TCK =0)
 - write data = **0Fh** into **CSRA1** (set TDI =0)
 8. Send 8-bit **IDCODE** instruction “**11111110**” (**FEh**) to EPROM. Repeat 8 times a process similar to step 7. LSB sent first, MSB sent last along with the TMS bit.
 9. Set **Update-IR** mode:
 - write data = **4Fh** into **CSRA1** (set TMS = 1)
 - write data = **CFh** into **CSRA1** (set TCK = 1)
 - write data = **4Fh** into **CSRA1** (set TCK = 0)
 - write data = **0Fh** into **CSRA1** (set TMS = 0).
 9. Set **Select-DR-Scan** mode:
 - write data = **4Fh** into **CSRA1** (set TMS = 1)
 - write data = **CFh** into **CSRA1** (set TCK = 1)
 - write data = **4Fh** into **CSRA1** (set TCK = 0)
 - write data = **0Fh** into **CSRA1** (set TMS = 0).
 10. Set **Capture-DR** mode:
 - write data = **0Fh** into **CSRA1** (set TMS = TCK = TDI =0)
 - write data = **8Fh** into **CSRA1** (set TCK =1)
 - write data = **0Fh** into **CSRA1** (set TCK =0).
 11. Set **Shift-DR** mode:
 - write data = **0Fh** into **CSRA1** (set TMS = TCK = TDI =0)
 - write data = **8Fh** into **CSRA1** (set TCK =1)
 - write data = **0Fh** into **CSRA1** (set TCK =0)
 - read **CSRA1[8]**. This is **bit 0** of the 32-bit IDCODE.
 12. Repeat step 12 31 times to get the other 1..31 bits of IDCODE.
 13. Set **Update-DR** mode
 - write data = **4Fh** into **CSRA1** (set TMS = 1)
 - write data = **CFh** into **CSRA1** (set TCK = 1)
 - write data = **4Fh** into **CSRA1** (set TCK = 0)

- write data = **0Fh** into **CSRA1** (set TMS = 0).

The IDCODE assigned to XC18V02 EPROM is **05025093h**. The IDCODE from the FPGA can be read out in a similar way. An example of the C++ program to reprogram the EPROM over VME can be found in [10].

1.5. CCB2004 Test with the TTCvi/TTCvx and TMB2005

The CCB2004 resides in the peripheral crate with at least one TMB2005 board. Optical connection to TTC source (a pair of TTCvi [3] and TTCvx [11] boards) is established. The test allows to verify internal functionality of the CCB2004 as well as distribution of the TTC broadcast commands and L1A signal over custom peripheral backplane to one or more TMB2005 [12] boards. The following procedures are required:

1. Verify that the TTC link is established (“**TTCRDY**” and “**QLOCK**” LED on the front panel are “on” and corresponding bits from **CSRA3[13]=CSRA3[14]=1**). Also make sure the FPGA was configured successfully (**CSRA3[12]=1**).
2. Make sure the “**CLK40**” LED on the front panel is blinking at a frequency of ~7Hz. If not, there is a problem with clock recovery/distribution from the TTCrx.
3. (Optional) read **CSRB17** and verify the date of the firmware revision.
4. Run VME access test: write, read and verify the content of **CSRB1...CSRB8**.
5. Initialize the CCB2004 as described in Section 1.1. Set “**Discrete Logic**” mode. Read **CSRB18** and verify the value returned on **CSRB18[7:0]** against the serial number of the CCB2004 board (labeled on the front panel).
6. Write data = **DF4h** into **CSRB1** (TTCrx is a source of broadcast commands, L1A from the TTCrx is enabled).
7. Write data = **4** into **CSR1** of TTCvi (address **\$80**) to enable L1A generation on VME command.
8. Write **any data** to address **Base+94h** on CCB2004 (reset L1ACC counter)
9. Write **any data** to address **Base+96h** on CCB2004 (enable L1ACC counter to count).
10. Write data = **1** into address **\$C4h** of TTCvi (broadcast command = **BCntRes**). Make sure the “**BCRES**” and “**CMDSTR**” LEDs on the front panel of the CCB2004 are blinking.
11. Write data = **2** into address **\$C4h** of TTCvi (broadcast command = **EvCntRes**). Make sure the “**EVCRES**” and “**CMDSTR**” LEDs on the front panel of the CCB2004 are blinking.
12. Write data = **4** into address **\$C4h** of TTCvi (broadcast command = **1**, or **BC0**). Make sure the “**BC0**” and “**CMDSTR**” LEDs on the front panel of the CCB2004 are blinking. Read back the **CSRB15** and verify that the returned value = **4**. Read back the **ADR_CCB_STAT** from available TMB2005 board(s) and verify that the returned value is “**1**” (note there is no 2-bit shift to the left in the **ADR_CCB_STAT** register).
13. Write data = **Ch** into address **\$C4h** of TTCvi (broadcast command = **3**, or **L1Reset**). Make sure the “**L1RES**” and “**CMDSTR**” LEDs on the front panel of the CCB2004 are blinking. Read back the **CSRB15** and verify that the returned

- value = **Ch**. Read back the **ADR_CCB_STAT** from available TMB2005 board(s) and verify that the returned value is “**3**” (note there is no 2-bit shift to the left in the **ADR_CCB_STAT** register).
14. Write data = **10h** into address **\$C4h** of TTCvi (broadcast command = **4**, or **Hard_Reset**). Make sure the “**HRESET**” and “**CMDSTR**” LEDs on the front panel of the CCB2004 are blinking. Read back the **CSRB15** and verify that the returned value = **10h**. Make sure the TMB2005 board(s) react to this command (LEDs on the front panel).
 15. Write data = **3Ch** into address **\$C4h** of TTCvi (broadcast command = **Fh**, or **CCB_Hard_Reset**). Make sure the “**CCBHR**” and “**CMDSTR**” LEDs on the front panel of the CCB2004 are blinking. Read back the **CSRB15** and verify that the returned value = **3Ch**.
 16. Write data = **40h** into address **\$C4h** of TTCvi (broadcast command = **10h**, or **TMB_Hard_Reset**). Make sure the “**HRESET**” and “**CMDSTR**” LEDs on the front panel of the CCB2004 are blinking. Make sure the TMB2005 board(s) react to this command (LEDs on the front panel).
 17. Write data = **4Ch** into address **\$C4h** of TTCvi (broadcast command = **13h**, or **MPC_Hard_Reset**). Make sure the “**HRESET**” and “**CMDSTR**” LEDs on the front panel of the CCB2004 are blinking. Make sure the MPC2004 reacts to this command (LEDs on the front panel).
 18. **Generate the other** short broadcast commands by writing corresponding codes into address **\$C4h** (TTCvi) and verifying the returned values from **CSRB15** (CCB2004) and **ADR_CCB_STAT** (TMB2005) registers.
 19. Check propagation of the **L1A** from the TTC source down to TMB2005 board(s):
 - write data = **1**, then data = **0** into **ADR_CNT_CTRL** of TMB2005 (clear all counters)
 - write **any data** to address **\$86h** of TTCvi (**N=1..100000**) times to generate (**N**) **L1A** pulses. Make sure the “**L1A**” LED on the front panel of the CCB2004 is blinking.
 - read back the data from **Base+90h** and **Base+92h** addresses of CCB2004 and verify the returned values against the number (**N**) of transmitted **L1A**
 - write data = **2** into **ADR_CNT_CTRL** of TMB2005 (take snapshot of current counter state)
 - write data = **2800h** into **ADR_CNT_CTRL** of TMB2005
 - read back the content of **ADR_CNT_RDATA** and verify against the number of **L1A** transmitted (lowest 16 bits)
 - write data = **2900h** into **ADR_CNT_CTRL** of TMB2005
 - read back the content of **ADR_CNT_RDATA** and verify against the number of **L1A** transmitted (highest 16 bits)
 - (Optional, only in “Discrete Logic” or “FPGA External” mode). The 12-bit Bunch and 24-bit Event counters are multiplexed on the **BCnt<11:0>** counter output bus of the TTCrx ASIC. Upon reception of an **L1A** signal, the TTCrx makes the content of these counters (depending on “Trigger Mode” as defined by bits 0 and 1 in the control register of the TTCrx) available on **BCnt<11:0>** bus with the respective strobes. These values are latched into the three registers **CSRB12-CSRB14** on the CCB2004 board

and available for read. The following steps are required to test this functionality:

- a. send **BCRES** and **EVCRES** broadcast commands from the TTC source (load data = **3** into **\$C4h** address on TTCvi)
 - b. send (**N**) **L1A pulses** from the TTC source
 - c. read **CSRB12** and make sure the returned value is changing (bunch counter counts permanently)
 - d. read **CSRB13** and **CSRB14** and verify the returned value against the values read out from the CCB2004 and TMB2005 (above). Note that the first event will be marked as event number zero, so the value in CSRB13 and CSRB14 should always be (**N-1**) while the content of L1A counters available from the CCB2004 and TMB2005 should be (**N**).
20. Check propagation of the long-format asynchronous cycles from the TTC:
- write data = **8001h** into address **\$C0h** of TTCvi (broadcast command with TTCrx=0)
 - write data = **0...FFFFh** into address **\$C2h** of TTCvi (send command)
 - make sure the “**DATSTR**” LED on the front panel of CCB2004 is blinking
 - read **CSRB16** and verify the returned value against the data in register **\$C2h**.
21. Switch to “**FPGA External**” mode:
- write data = **Eh** into **CSRA1**
 - write data = **DFE9h** into **CSRB1**
- Repeat steps 7-21.**
22. Switch to “**FPGA Internal**” mode:
- write data = **Eh** into **CSRA1**
 - write data = **DFE9h** into **CSRB1** (CSRB2 is a source of short broadcast commands, CSRB3 is a source of long commands, L1A will be generated on VME command).
23. **Repeat steps 8-20** with the **CSRB2** as a source of short broadcast commands (instead of register \$C4h) and **CSRB3** as a source of long commands instead of register \$C2h). Write any data to address **Base+54h** on CCB2004 to generate the L1A pulse.
24. (Optional). Check propagation of the TMB_L1A_Request signal from the TMB2005 to CCB2004. This signal causes generation of L1A, when enabled. The following steps are required:
- write data = **DFDEh** into **CSRB1** (Enable TMB_L1A_Request)
 - write data = **1**, then data = **0** into **ADR_CNT_CTRL** of TMB2005 (clear all counters)
 - initialize the TMB_L1A_Request generator on TMB2005 board. The generator starts generating 25 ns L1A_Request pulses (at ~3MHz frequency) on “Start Trigger” and stops generating on “Stop Trigger” commands:
 - a. write data = **3dh** into **ADR_CCB_CFG** of TMB2005

- b. write data = **7204h** into **ADR_CCB_TRIG**
- c. write data = **0** into **ADR_ALCT_INJ**
- d. write data = **5h** into **ADR_ALCT_INJ**
- e. write data = **85h** into **ADR_ALCT_INJ**
- f. write data = **3** into **ADR_TMBTIM**
- g. write data = **FFE0h** into **ADR_CFEF_INJ**
- h. write data = **3FFh** into **ADR_SEQ_TRIG_EN**
- i. write data = **7C00h** into **ADR_TRIG_EN**
- j. write data = **FFFh** into **ADR_SEQ_L1A**
- k. write data = **1** into **ADR_TRIG_EN**
- l. write data = **FFFDh** into **ADR_ALCT_INJ**
- m. write data = **1** into **ADR_CCB_CMD**
- n. write data = **603h** into **ADR_CCB_CMD** (“Start Trigger”)
- o. write data = **1** into **ADR_CCB_CMD**
- p. write data = **103h** into **ADR_CCB_CMD** (“BC0”)
- q. write data = **1** into **ADR_CCB_CMD**
- r. write data = **7FFFh** into **ADR_CFEF_INJ_ADR**
- s. write data = **8000h** into **ADR_CFEF_INJ_ADR**
- t. write data = **7FFFh** into **ADR_CFEF_INJ_ADR**
- u. write data = **1** into **ADR_CCB_CMD**
- v. write data = **703h** into **ADR_CCB_CMD** (“Stop Trigger”)
- w. write data = **1** into **ADR_CCB_CMD**
- read back the content of **Base+90h** and **Base+92h** registers of CCB2004
- write data = **2** into **ADR_CNT_CTRL** of TMB2005 (take snapshot of current counter state)
- write data = **2800h** into **ADR_CNT_CTRL** of TMB2005
- read back the content of **ADR_CNT_RDATA** and verify it against the value that was read out from the **Base+90h** address (lowest 16 bits)
- write data = **2900h** into **ADR_CNT_CTRL** of TMB2005
- read back the content of **ADR_CNT_RDATA** and verify it against the value that was read out from the **Base+92h** address (highest 16 bits).

1.6. CCB2004 Test in the Track Finder Crate

Repeat steps 1-5 described in Section 1.5. Make sure the “**NO LOCK**” LED on the front panel of all SP05 boards in the Track Finder crate is “off” (the QPLL on SP05 board must be locked to the backplane clock provided by CCB2004).

The SP05 firmware allows to analyze timing of the CCB2004 command strobe with respect to the SP05 system clock, as well as the CCB2004 command itself, in the CCB analyzer STS_ANA [13]. The analyzer is 64 words deep and available for read from VME. To check command transmission from the CCB2004 to SP05 the following steps are required:

- set SP05 under the CCB fast control (write “**0**” into **CSR_FCC**)
- reset CCB analyzer (write **any data** into **STS_ANA**)
- send 1..64 sample commands from the CCB2004

- read 1..64 words from STS_ANA and verify them against expected values. Make sure the VME_FPGA on SP05 board samples the CCB command in the middle of the valid sample. See Section STS_ANA in [13] for more details.

1.7. Response to External Resets

The CCB2004 response to various external resets is summarized below.

1. **Power cycling** sets all the TTCrx internal registers into default values (see Table 3 in [2]) and loads “0” into all the CSRBi registers in the FPGA.

2. **Hard reset** from the TTC or **Hard reset** upon writing any data into CSRA2 or **Hard reset** upon writing any data into (base address +60) **DOES NOT** change the state of the TTCrx internal registers.

3. **Hard reset** from the TTC or **Hard reset** upon writing any data into CSRA2 or **Hard reset** upon writing any data into (base address +60) **DOES NOT** change the state of the CSRA[1..3] registers.

4. **Hard reset** from the TTC or **Hard reset** upon writing any data into CSRA2 will reset all the CSRb registers in the FPGA into “0” if the S10-8 switch is set “on”. By default this switch is set “off” on all production CCB2004 boards, so the **Hard reset** does not affect the FPGA.

5. **TTCrx reset pulse** (write any data into (base+5C) address of the CCB) initiates a **FULL reset procedure** of the TTCrx ASIC. All the TTCrx internal registers will be loaded with their default values. This command works in any CCB mode. Also on this command a 14-bit ID is loaded into the TTCrx. **It must be issued during initialization for proper operation from the TTC and I²C sources. Three other possible partial TTCrx resets:**

- (1) Write to individual subaddress = 6 via TTC (see page 21 in [2])
- (2) I²C reset (write "5" into status register, see page 30 in [2])
- (3) timeout condition in the watchdog circuit (see page 33 in [2])

will load the default values into all the TTCrx internal registers **WITH THE EXCEPTION** of the fine delay 1 and 2, coarse delay and the control registers.

6. FPGA “**Soft Reset**” (write any data into CSRA3) command enables propagation of the selected L1A and “external trigger” signals to custom backplane (in the “FPGA” mode) and propagation of the selected L1A to the front panel connector (in the “FPGA” or ‘Discrete Logic’ modes), disables 32-bit L1A counter and resets the CSRb11[10..8] bits. It does not affect the content of all other CSRb[1..18] registers.

References

- [1] CCB'2004 Specification. <http://bonner-ntserver.rice.edu/cms/CCB2004P.pdf>
- [2] TTCrx Reference Manual. Version 3.10, August 2005. Available at http://bonner-ntserver.rice.edu/cms/TTCrx_manual3.10.pdf
- [3] TTC-VMEbus Interface TTCvi-MkII. <http://bonner-ntserver.rice.edu/cms/ttcvi.pdf>
- [4] I²C Manual. Philips Application Note AN10216-01. March 24, 2003. Available at: http://www.semiconductors.philips.com/acrobat_download/applicationnotes/AN10216_1.pdf. See also The I²C-Bus Specification Version 2.1 January 2000. Available at http://www.nxp.com/acrobat_download/literature/9398/39340011_21.pdf
- [5] <http://www.bonner.rice.edu/~sangjoon/CMS/EmtTests/Src/ccb2004I2CA11.cpp>
- [6] DS2401 Silicon Serial Number Specification. Available at <http://pdfserv.maxim-ic.com/en/ds/DS2401.pdf>
- [7] <http://www.bonner.rice.edu/~sangjoon/CMS/EmtTests/Src/ccb2004ChipId.cpp>
- [8] <http://bonner-ntserver.rice.edu/cms/projects.html#ccb>
- [9] <http://direct.xilinx.com/bvdocs/publications/ds026.pdf>
- [10] <http://www.bonner.rice.edu/~sangjoon/CMS/Jtag/>
- [11] <http://bonner-ntserver.rice.edu/cms/ttcvx.pdf>
- [12] <http://www-collider.physics.ucla.edu/cms/trigger/striplct.html>
- [13] http://www.phys.ufl.edu/~uvarov/SP05/LU-SP_Backplane_Interfaces_060701s.pdf

2. Muon Port Card MPC2004

This User's Guide should be used together with the MPC2004 Specification [1].

2.1. Initialization

After power cycling make sure that the six green LEDs on the front panel indicating active on-board powers as well as the "DONE" LED (FPGA was successfully configured from its EPROM) are "on". Make sure that the "CLK40" LED on the front panel is blinking (~7Hz). This means that the main 40Mhz clock on MPC2004 board is active. Then:

1. Read **CSR0**. Make sure the CSR0[12]=1 (which means the FPGA was successfully reloaded from the EPROM).
2. (Optional). Read **CSR1** and check the date of the firmware revision.
3. Program **CSR0** with the Board_ID[5..0], FPGA_Mode, CSR0[13]=1 (by default, set the clock in the middle of the "safe window"), CSR0[14]=1 (enable all serializers), CSR0[15]=0 (normal mode of operation) or CSR0[15]=1 (to run a PRBS test of optical links to Sector Processor).

Note: Bit CSR0[13] is effective only if the on-board switch S2-2 is "on" and S2-1 is "off". Switch S2 selects the source of the 40MHz clock (fixed clock from the CCB2004 or adjustable clock with the delay element) for the FPGA. If S2-2 is "off" and S2-1 is "on", the fixed CCB2004 clock is chosen. This clock is set approximately in the middle of the "safe window".

4. Send "Soft_Reset" (write any data to address **600004h**). This command resets all the FIFO buffers in the FPGA. It does not affect any CSR registers. "Hard_Reset" command is intended for recovery from possible Single Event Upsets in the LHC environment. It is not necessary to send the "Hard_Reset" during initialization.
5. (Optional). Load **CSR2** if needed. By default (after power cycling or "Hard_Reset"), CSR2="0".
6. (Optional). Load **CSR4** if the "transparent" mode will be used. By default (after power cycling or "Hard_Reset") CSR4=0, and the MPC2004 is in a "sorter" mode.

2.2. 1-Wire Interface

1-Wire bus is intended for obtaining a unique 64-bit serial ID number from the DS2401 chip. The CSR6 should be used. Its bit assignment is identical to CSR6 on CCB2004 (see Section 1.3 for more details), so the same program can be used to read the ID from both the CCB2004 and MPC2004 boards.

2.3. JTAG Access to FPGA and EPROM and Firmware Upgrade

One Xilinx XCV600E-8FG680 FPGA and one XC18V04 EPROM are located on the mezzanine board. Both devices can be accessed over JTAG bus. JTAG protocol can be emulated using write and read operations directed to CSR0[8..5]. Xilinx Parallel Cable IV can be used as well. An on-board switch S8-1 defines which of these two options is set. The FPGA is the 1st device in a JTAG chain, and the EPROM is the 2nd one. Files with the .mcs and .svf extension (produced by Xilinx ISE development system) are needed to reprogram the EPROM with the Xilinx downloading cable or VME path respectively. The most recent versions of downloading files can be found in [2].

An IDCODE from XC18V04 EPROM can be obtained over JTAG as described in Section 1.4. Note that the BYPASS instruction for Virtex-E FPGA is a 5-bit “11111”. The IDCODE assigned to XC18V04 EPROM is **05026093h**.

An example of the code to reprogram the XC18V04 over VME can be found in [3].

2.4. MPC2004 Self-Test

The MPC2004 is located in the peripheral crate (slot 12) and set to a “Test” mode. Data patterns are loaded into FIFO_A, sent through the sorter unit and checked out from the FIFO_B. All FIFO buffers are 511 words deep. The procedures are the following:

1. Write **any data** to address **600004h** of MPC2004 (generate “**Soft_Reset**” to the FPGA).
2. **Initialize the CCB2004** board in the peripheral crate in “Discrete Logic” or “FPGA External” mode and **generate a “Soft_Reset”** for the CCB2004 (Section 1.1 above).
3. Write data = **6A01h** into **CSR0** (set “Test” mode).
4. Read **CSR3** and make sure the returned value is **A(hex)** (both FIFO_A and FIFO_B buffers are empty).
5. Load **255 32-bit words (510 frames)** of data into **FIFO_A[1..9]**. They will represent the incoming LCT’s for the sorter unit.
6. Load the last word (2 frames) = **0** into all **FIFO_A[1..9]** buffers.
7. Send **broadcast command = 30h** from the TTC source to inject data from FIFO_A into the sorter unit.
8. Read **CSR3** and make sure that FIFO_A is empty and FIFO_B is not empty (if the patterns in FIFO_A were representing valid LCT’s).
9. **Read 510 words** from **FIFO_B[1..3]** and verify they are equal to expected values according to FIFO_A content and the sorting algorithm.
10. Read **CSR3** and verify the returned value is **Ah** (both FIFO_A and FIFO_B buffers are empty).

2.5. TMB2005 – to – MPC2004 Data Transmission Test

This test involves the CCB2004, MPC2004 and 1..9 TMB2005 boards residing in the EMU peripheral crate. Understanding of the TMB2005 functionality, and its internal registers is essential for this test, see [4] for details. This test also allows to measure the “safe window” (i.e. the fraction of the 80Mhz clock period within which the data from all nine TMB2005 boards can be safely latched in into the MPC2004). The following procedures are needed:

1. Program CCB2004 in the peripheral crate (slot 13):
 - write data = **0** into **CSRA1** (set “FPGA” mode)
 - write data = **FFFFh** into **CSRB1** (set “Internal” mode)
 - write **any data** to **CSRA3** (generate “**Soft_Reset**”)
2. (Optional; required only if the CCB2004 is in “Discrete Logic” mode) Initialize the TTCrx ASIC from the TTC source as described in Section 1.1 above.
3. Program and initialize the MPC2004 (slot 12):
 - write **any data** into address **600004h** (generate “**Soft_Reset**” to the FPGA)
 - (Optional) read back **CSR3** and make sure the returned value is **Ah** (both FIFO_A and FIFO_B buffers are empty)
 - write data = **4A1Eh** into **CSR0** (set “Trigger” mode)
 - write data = **3000h** into **CSR2** (adjust input clock in the middle of “safe window”).
4. Initialize every TMB2005 board in the crate:
 - write data = **A11Bh** into **ADR_TMB_TRIG** (set `mpc_rx_delay[3:0]= 8`)
 - write data = **02FFh** into **ADR_MPC_INJ** (enable injector start by TTC command; number of LCT pairs to inject = 255, or 510 frames).
5. Program LCT patterns to be injected into MPC2004 on every TMB2005 board:
 - a. Load the **1st frame of LCT0** into **ADR_MPC_RAM_WDATA**
 - write data = **0** into **ADR_MPC_RAM_ADR**
 - write data = **1** into **ADR_MPC_RAM_ADR**
 - write data = **0** into **ADR_MPC_RAM_ADR**
 - b. Load the **2nd frame of LCT0** into **ADR_MPC_RAM_WDATA**
 - write data = **0** into **ADR_MPC_RAM_ADR**
 - write data = **2** into **ADR_MPC_RAM_ADR**
 - write data = **0** into **ADR_MPC_RAM_ADR**
 - c. Load the **1st frame of LCT1** into **ADR_MPC_RAM_WDATA**
 - write data = **0** into **ADR_MPC_RAM_ADR**
 - write data = **4** into **ADR_MPC_RAM_ADR**
 - write data = **0** into **ADR_MPC_RAM_ADR**
 - d. Load the **2nd frame of LCT1** into **ADR_MPC_RAM_WDATA**
 - write data = **0** into **ADR_MPC_RAM_ADR**
 - write data = **8** into **ADR_MPC_RAM_ADR**
 - write data = **0** into **ADR_MPC_RAM_ADR**
6. Repeat step 6 for other LCT patterns (maximum 255 pairs of LCT0+LCT1). Note the `mpc_adr[7:0]` in **ADR_MPC_RAM_INJ** should increase for every pair (four frames) of LCTs. For example, the second pair of LCT0+LCT1 should be loaded as shown below:

- a. Load the **1st frame of LCT0** into **ADR_MPC_RAM_WDATA**
 - write data = **0100h** into **ADR_MPC_RAM_ADR**
 - write data = **0101h** into **ADR_MPC_RAM_ADR**
 - write data = **0100h** into **ADR_MPC_RAM_ADR**
 - b. Load the **2nd frame of LCT0** into **ADR_MPC_RAM_WDATA**
 - write data = **0100h** into **ADR_MPC_RAM_ADR**
 - write data = **0102h** into **ADR_MPC_RAM_ADR**
 - write data = **0100h** into **ADR_MPC_RAM_ADR**
 - c. Load the **1st frame of LCT1** into **ADR_MPC_RAM_WDATA**
 - write data = **0100h** into **ADR_MPC_RAM_ADR**
 - write data = **0104h** into **ADR_MPC_RAM_ADR**
 - write data = **0100h** into **ADR_MPC_RAM_ADR**
 - d. Load the **2nd frame of LCT1** into **ADR_MPC_RAM_WDATA**
 - write data = **0100h** into **ADR_MPC_RAM_ADR**
 - write data = **0108h** into **ADR_MPC_RAM_ADR**
 - write data = **0100h** into **ADR_MPC_RAM_ADR**.
7. (Optional) Read back the content of **MPC_RAM** from every TMB2005 board. To do this, use bits **mpc_ren[3:0]** of **ADR_MPC_RAM_ADR** instead of **mpc_wen[3:0]** in the examples above. Read data from **ADR_MPC_RAM_RDATA** register.
 8. Send the TTC broadcast command = **24h** (“**Inject test patterns from the TMB**”)
 9. (Optional) Read **CSR3** of MPC2004 and make sure **FIFO_B** is not empty (if valid patterns from TMB2005 boards are expected).
 10. Read **FIFO_B[1..3]** from MPC2004 (**255 words = 510 frames**) and verify the returned values against expected, according to number of participating TMB2005 boards, content of their **MPC_RAM**, and sorting algorithm of the MPC2004.
 11. (Optional) Read **CSR3** of MPC2004 and verify the **FIFO_B** is empty.
 12. Read “winner bits” (called **mpc_accept[1:0]** in the TMB manual [4]) from the injector RAM of all participating TMB2005 boards. To do this:
 - a. Load **ADR_MPC_RAM_ADR** to be read out, starting from address **0** for **mpc_adr[7:0]; mpc_wen[3:0]=mpc_ren[3:0]=0**
 - b. Read **ADR_MPC_INJ**, check bits **mpc_accept[1:0]** and verify that they correspond to results of sorting for specific patterns loaded into this TMB2005.

Note 1: Due to TMB-to-MPC-to-TMB propagation delays, the first several (usually, eight) words in the injector RAM will have the “MPC accept bits” [11:10] (“winners”) = “0” and only the ninth and further words will represent the real MPC2004 “winner” responses.

Note 2: The four “MPC accept response delay” bits in the ADR_TMB_TRIG register do not affect the content of the injector RAM with “winner” responses. These four bits specify the delay (by default = 7) to latch the two “mpc_accept[1:0]” bits into the ADR_TMB_TRIG register.
 - c. Increase **mpc_adr[7:0]** (up to **FFh**) and go to step b) above.

To measure the “safe window”, the value loaded into the CSR2 on Step 3, should vary typically between 2000h to 4000h (use 2100h, 2200h... 4000h); each step corresponds to 0.25 ns. For each step we recommend to run 300..500 iterations (up to 1000 iterations on the boundaries of the “safe window”); each iteration comprises 255 random data patterns to be loaded into every TMB2005. The “safe window” corresponds to error-free data transmission. Based on our experience, the average “safe window” is ~5.5 ns (**CSR2[15:8]=25h..3Bh**). Note the S2-1 on MPC2004 board should be “off” and S2-2 “on” to allow this test. If S2-1 is “on” and S2-2 “off”, the clock will be automatically set approximately in the middle of the “safe window” and the test should show no errors for any value in CSR2. It is essential that all the nine TMB2005 boards participate in this measurement.

2.5.1. Simplified TMB2005 – to – MPC2004 data transmission test

The goal of the test is to quickly check data transmission (2 LCTs only) from one of nine TMBs in the fully loaded peripheral crate. The following procedures are needed:

1. Program CCB2004 in the peripheral crate (slot 13):
 - write data = **0** into **CSRA1** (set “FPGA” mode)
 - write data = **1** into **CSRB1** (set “Internal” mode)
2. Program and initialize the MPC2004 (slot 12):
 - write **any data** into address **600004h** (generate “**Soft_Reset**” to the FPGA)
 - write data = **6A1Eh** into **CSR0** (set “Trigger” mode, set input clock in the middle of the “safe window”).
3. Enable sending data to MPC from one selected TMBn (n=1..9), disable all others:
 - write data = **A11Bh** into **ADR_TMB_TRIG** (set `mpc_rx_delay[3:0]=8`) register of the selected TMB
 - write data = **020Ah** into **ADR_MPC_INJ** (enable injector start by TTC command; number of LCT pairs to inject = 10) of the selected TMB
 - write data = **0** into **ADR_MPC_INJ** (disable injector start by TTC command; number of LCT pairs to inject = 0) of all other TMBs
4. Program LCT patterns to be injected into the MPC2004 on selected TMB2005 board: For the first word:
 - a. Load the **1st frame of LCT0 = AAAAh** into **ADR_MPC_RAM_WDATA**
 - write data = **0** into **ADR_MPC_RAM_ADR**
 - write data = **1** into **ADR_MPC_RAM_ADR**
 - write data = **0** into **ADR_MPC_RAM_ADR**
 - b. Load the **2nd frame of LCT0 = 5555h** into **ADR_MPC_RAM_WDATA**
 - write data = **0** into **ADR_MPC_RAM_ADR**
 - write data = **2** into **ADR_MPC_RAM_ADR**
 - write data = **0** into **ADR_MPC_RAM_ADR**
 - c. Load the **1st frame of LCT1 = 9999h** into **ADR_MPC_RAM_WDATA**
 - write data = **0** into **ADR_MPC_RAM_ADR**
 - write data = **4** into **ADR_MPC_RAM_ADR**
 - write data = **0** into **ADR_MPC_RAM_ADR**
 - d. Load the **2nd frame of LCT1 = 4444h** into **ADR_MPC_RAM_WDATA**
 - write data = **0** into **ADR_MPC_RAM_ADR**

- write data = **8** into **ADR_MPC_RAM_ADR**
 - write data = **0** into **ADR_MPC_RAM_ADR**
5. Load the other 9 words with **data=0** (increase address for every other word)
 6. Write data = 90h into address 680022h of CCB (send the TTC command = **24h** (“**Inject test patterns from the TMB**”). Make sure that two LEDs on the front panel of MPC (MUON1 and MUON2) are blinking.
 7. Read data from address **6000A4** (FIFO_B1) of MPC. Make sure it is = **AAAAh**.
 Read data from address **6000A4** (FIFO_B1) of MPC. Make sure it is = **5555h**.
 Read data from address **6000A6** (FIFO_B2) of MPC. Make sure it is = **9999h**.
 Read data from address **6000A6** (FIFO_B2) of MPC. Make sure it is = **4444h**.
 Read data from address **6000A8** (FIFO_B3) of MPC. Make sure it is = 0.
 Read data from address **6000A8** (FIFO_B3) of MPC. Make sure it is = 0.
- Make sure the FIFO_B buffer is empty at this point (“FBEM” LED is on).
8. Read **ADR_TMB_TRIG (86)** from selected **TMB2005**. Make sure **data=A71Bh** (two bits **mpc_accept[1:0]=1** were added to initial value of A11Bh).
 9. Read “winner bits” from the injector RAM of the selected TMB2005 board:
 - a. Load **ADR_MPC_RAM_ADR** to be read out, starting from address **0** for **mpc_adr[7:0]; mpc_wen[3:0]=mpc_ren[3:0]=0**
 - b. Read **ADR_MPC_INJ** and check bits **mpc_accept[1:0]**. We suggest to read 10 words. Due to TMB-to-MPC-to-TMB propagation delays the first few (usually eight) words will have the “winner bits” empty. The results should look like this:
 - **word 1: 20Ah**
 - **word 2: 20Ah**
 - **word 3: 20Ah**
 - **word 4: 20Ah**
 - **word 5: 20Ah**
 - **word 6: 20Ah**
 - **word 7: 20Ah**
 - **word 8: 20Ah**
 - **word 9: E0Ah (both “winner bits” present here)**
 - **word 10: 20Ah.**

2.6. Test of optical links with the PRBS patterns

The TLK2501 transceiver has an embedded pseudo-random bit stream (PRBS) generator that makes testing of optical links between the MPC2004 and SP05 boards [5] quite simple. The following steps are required:

1. Establish connection (all three links) between the MPC2004 under the test and SP05.
2. Write data = **CA00h** into **CSR0** of MPC2004 (program PRBS mode).
3. Write data = **50h** into **CSR_LNK** register of SP05 for all three links under test.
4. Write data = **1Fh** into **ACT_LCR** to reset all error counters on SP05 board for selected links.
5. Make sure that three yellow LEDs on the front panel of the SP05 for selected links are “on”. At this point the PRBS is running continuously.

6. Read three **CSR_LNK** registers of SP05 for selected links in a loop and make sure the returned values are **750h** (all error counters = 0). See more details on CSR_LNK register in the SP05 manual [5].

2.7. Test of optical links with the programmable data patterns

The MPC2004 is located in the peripheral crate, and the SP05 board is located in the Track Finder crate. The CCB2004 boards in both crates are connected to the TTC clock and command source (TTCvi or TTCci board) in one of these two crates or in a separate crate. The TMB boards are not involved in this test, so the MPC2004 is in a ‘Test’ mode.

1. Program CCB2004 in both crates:
 - **Initialize both CCB2004** boards in the peripheral and Track Finder crates as described in Section 1.1 of this Guide
 - Set both CCB2004 into ‘Discrete Logic’ mode (load ‘1’ into **CSRA1**)
 - Send ‘**Soft_Reset**’ to both CCB2004 (write **any data** to **Base+4** address)
 - Make sure the TTCrx on both CCB2004 boards are ‘Ready’ and OPLL are ‘Locked’ (check corresponding LEDs on the front panel or/and read **CSRA3**).
2. Establish connection (all three links) between the MPC2004 under test and the SP05 (use only one triple link out of F1..F5, typically the bottom F1). Optical fibers can be of different length.
3. Program MPC2004 in the peripheral crate:
 - send ‘**Soft_Reset**’ to FPGA on MPC2004 (write **any data** into **600004h**)
 - write data = **6A1Fh** into **CSR0** (note: Board_ID[5:0] can be any)
 - load 255 programmable LCT patterns (510 frames) into **FIFO_A[9..1]**
 - load the last pattern = **0** into all **FIFO_A[9..1]** buffers.
4. Program SP05 in the Track Finder crate:
 - write data = **0** into **CSR_FCC VM** (set SP05 to CCB control)
 - write data = **10h** into **CSR_LNK FA MA** (enable all three links)
 - write data = **9050h** into **CSR_SFC VM** (set delay of spy FIFO write)
 - write data = **11FFh** into **CSR_SFC FA MA** (set how many words to expect)
 - write data = **31FFh** into **CSR_SFC SP** (set spy FIFO window)
 - write data = **4h** into **ACT_XFR FA MA** (reset spy FIFO)
 - write data = **4h** into **ACT_XFR SP** (reset spy FIFO)
 - write data = **6Dh** into **CSR_AFD FA MA** (set alignment FIFO read delay)
5. Send **L1Reset** broadcast command (=3h) from the TTC source to both CCB2004 boards.
6. Send ‘**Inject patterns from MPC**’ command (=30h) from the TTC source to both CCB2004 boards.
7. Read 255 patterns (510 frames) from **FIFO_B[3..1]** on MPC2004 and make sure they satisfy with the sorting criteria.
8. Read 255 patterns (510 frames) from **DAT_SF F1 M1/M2/M3** (for each muon) and make sure they satisfy with the sorting criteria and coincide with the data read out of **FIFO_B[3..1]** on MPC2004.
9. Read **CSR_SF** spy FIFO status and make sure the spy FIFO is empty (**SFEF=1**).

10. Read **CSR_BID** and make sure the **MPC_LINK_ID[7:0]** is equal to expected number (**MPC_ID[5:0]**) as pre-programmed into the CSR0 of MPC2004 and **LINK_ID[1:0]** as hard-wired on SP05).

Note: You will probably need to adjust the delay of spy FIFO write (in CSR_SFC VM) and the delay of alignment FIFO read (in CSR_AFD FA).

References

- [1] MPC2004 Specification. <http://bonner-ntserver.rice.edu/cms/MPC2004P.pdf>
- [2] <http://bonner-ntserver.rice.edu/cms/projects.html#mpc>
- [3] <http://www.bonner.rice.edu/~sangjoon/CMS/Jtag/>
- [4] <http://www-collider.physics.ucla.edu/cms/trigger/striplct.html>
- [5] http://www.phys.ufl.edu/~uvarov/SP05/LU-SP_Backplane_Interfaces_060701s.pdf,
See also <http://www.phys.ufl.edu/~uvarov/SP05/SP05.htm>

3. Muon Sorter MS2005

This User's Guide should be used together with the MS2005 Specification [1].

3.1. Initialization

After power cycling make sure that the four green LEDs on the front panel indicating active on-board powers as well as the "DONE" LED (FPGA was successfully configured from its EPROM) are "on". Make sure that the "CLK40" LED on the front panel is blinking (~7Hz). This means that the main 40MHz clock on MS2005 board is active. Then:

1. Write data = **12A0h** into **CSR0** (set "Trigger" mode).
2. (Optional) Read **CSR4** and check the date of the firmware revision.
3. Make sure the **CSR3[0]='1'** (FPGA was configured and locked successfully).
4. Send "**Soft_Reset**" (write **any data** to address **700018h**). This command resets all the FIFO buffers in the FPGA. It does not affect any CSR registers. "Hard_Reset" command is intended for recovery from possible Single Event Upsets in the LHC environment. It is not necessary to send "Hard_Reset" during initialization. After power cycling the "Hard_Reset" is disabled. To enable it, the CSR4[1] should be set to "1".
5. Program **CSR9[11..0]** to enable or disable input data streams from a specific Sector Processor(s) in the Track Finder crate. After power cycling all the SP's are enabled.
6. Program **CSR8**. All the 12 data streams from SP1..SP12 are latched into the main Xilinx FPGA on a common 80Mhz clock that is derived from the Master 40Mhz provided by the CCB2004 board. This clock is produced inside the FPGA using its Digital Control Module (DCM, see [2]) and must be set in the middle of the "safe window" for all 12 SP sources. Fine clock adjustments within the 12.5 ns

clock period can be done using two independent methods. **The first (A) method is preferred.**

- A. The Master 40Mhz clock from the CCB2004 passes through the 3D7408-025 [3] delay chip before it reaches the FPGA. The delay is programmable with the **CSR8[7..0]** and the minimal step of adjustment is 250 ps. This delay value can be programmed in such a way that the 80Mhz clock produced from the delayed 40Mhz Master clock will be set exactly in the middle of the “safe window”. It was measured that the “safe window” corresponds to $CSR8=78..101(\text{dec})$, so the recommended setting is **CSR8=89(dec)=59h**. Then it is not necessary to program the DCM1 which delay is set to “0” automatically on power cycling.
- B. For a fixed value of CSR8, the resulting 80Mhz clock within the FPGA can be delayed using the DCM1 with a 100 ps precision and set in the middle of the “safe window”. It is recommended to program **CSR8[7..0]=0** (this is also a default value after power cycling). Then, according to our measurements, the “safe window” corresponds to DCM1 settings between -66 and +7. The middle of the “safe window” corresponds to DCM1 setting of -30. The procedure to program the DCM1 with value = “-30” is the following:
 - B.1. Write “0” to address **700160h** (set up fine phase adjustment for DCM1)
 - B.2. Read **CSR5** and make sure the $CSR5[0]=1$ (clock de-skew was done)
 - B.3. Write **any data** to address **700164h** (reset PSDONE status bit)
 - B.4. Repeat B.1.-B.3. **29 times**.
7. Write **any data** to **70016Ah** address (set “winner bit” mode).
8. Load all Rank and Phi **LUT RAM’s** and (optional) read them back for verification.

3.2. JTAG Access to FPGA and EPROM and Firmware Upgrade

The Xilinx XCR3128 PLD on the main MS2005 board performs the VME A24D16 slave functions and controls the operation of the Fairchild SCANPSC100 controller [4]. This controller supports VME accesses to the Xilinx XC2V4000-5FF1152C FPGA and four XC18V04 EPROM’s located on the mezzanine board.

The PLD can be programmed over Xilinx Parallel Cable IV only using an on-board 14-pin connector P11. File with the .jed extension for the PLD can be found in [5]. Four EPROM’s can be programmed over Parallel Cable IV as well using another on-board 14-pin connector P10. Note that $CSR4[0]$ should be set to “1” to enable the SCANPSC100 controller. By default the $CSR4[0]=0$ and the cable connection is enabled.

Files with the .mcs and .svf extensions (produced by Xilinx ISE development system) are needed to reprogram the EPROM with the Xilinx Parallel Cable and VME path respectively. The most recent versions can be found in [5].

To reprogram the EPROMs over VME the following steps are needed:

1. Write data = 1 into **CSR4**.

2. Use **LoadFPGAconsole.exe**, which is a UF program to load the SP firmware, with the following flags:
`LoadFPGAconsole.exe -s14 -j0 -x[SP xml file] [MS svf file]`

3.3. MS2005 Self-Test

The MS2005 is set to “Test” mode. Data patterns are loaded into FIFO_A, sent through the sorter unit and checked out from FIFO_C and FIFO_B. All FIFO buffers are 511 words deep. An external cable can be connected between one of the output connectors on the front panel and the P12 connector on the main board. Then the results of sorting after LUT conversion will be stored in FIFO_D. The required procedures are the following:

1. Write **any data** into address **700018h** (generate “**Soft_Reset**” for the FPGA).
2. Initialize the CCB2004 board in the Track Finder crate in “**Discrete Logic**” or “**FPGA External**” mode and generate a “**Soft_Reset**” for the CCB2004.
3. Write data = **A2A1h** into **CSR0** (address **700158h**).
4. Load the **Rank+Phi LUT** content for all four muons (see Section 3.1 in [1]):
 - use addresses **700400h..7007FEh** for LUT corresponding to **muon1**
 - use addresses **700800h..7007BEh** for LUT corresponding to **muon2**
 - use addresses **700C00h..7007FEh** for LUT corresponding to **muon3**
 - use addresses **701000h..7013FEh** for LUT corresponding to **muon4**
5. Read **CSR1** and make sure the returned value is **AAh** (all FIFO buffers are empty).
6. Load 255 32-bit words (510 frames) of data into **FIFO_A[1..12]**. They will represent the 255 incoming muon patterns for the sorter unit.
7. Load the last word (2 frames) “**0**” into all **FIFO_A[1..12]** buffers.
8. Send the “**Inject patterns from MS**” broadcast command (=31h) from the TTC source (or write **any data** to address **70015Eh** to emulate this command).
9. Read **CSR1** and make sure that **FIFO_A** is empty and the other FIFO’s are not empty (if the patterns in FIFO_A were representing valid muons).
10. Read 510 32-bit words of data from **FIFO_C[1..4]** and make sure they are equal to expected values according to FIFO_A content and the sorting algorithm.
11. Read 510 32-bit words of data from **FIFO_B[1..4]** and make sure they are equal to expected values according to FIFO_A content, the sorting algorithm and LUT content.
12. Read 510 32-bit words of data from **FIFO_D** and make sure they are equal to expected values according to FIFO_A content, the sorting algorithm, LUT content and required data format conversion (see Notes to Table 11 in [1]) for the selected connection between the front panel output and P12 connector.
13. Read **CSR1** and make sure the returned value is **AAh** (all the FIFO buffers are empty).

3.4. MS2005 – to – GMT Data Transmission Test

The test involves the MS2005 board residing in the CSC Track Finder crate and the Global Muon Trigger (GMT) receiver board residing in the GMT/GT crate [6]. The clock

and commands should arrive to both crates from the same TTC source. In order to simplify the MS2005 – to – GMT testing procedures, we have implemented a dedicated RAM buffers in the main MS2005 FPGA. These buffers keep patterns representing the four output muons being sent to the GMT receiver (see Section 6 in [1]). The procedures to run a MS2005 – to – GMT test using these RAM buffers are the following:

1. Write **any data** into address **700018h** (generate “**Soft_Reset**” for the FPGA).
2. Initialize the CCB2004 board in the TF crate in “**Discrete Logic**” or “**FPGA External**” mode and generate a “**Soft_Reset**” for the CCB2004.
3. Initialize the GMT receiver board as needed.
4. Write data = **A4A1h** into **CSR0** address **700158h** (set CSR0[10]=1 to use the RAM buffers as data sources for the GMT receiver).
5. Write data = **1** into **CSR6[7..0]** to select the 1st RAM buffer and select the command source in **CSR7[11..8]**.
6. Write data = **0** into RAM address counter (address **700178h**).
7. Write 16-bit test pattern into address **70017Ch**.
8. Increment (up to **1FFh**) the address, load it into address counter and go to step 7 above.
9. Load the other RAM buffers (use values **CSR6[7..0] = 2, 4, 8, 16, 32, 64, 128**) and go to step 6 above.
10. (Optional) Read back all **RAM buffers** for verification.
11. Send **BC0** or **BCntRes** broadcast command from the TTC source, depending on your choice in **CSR6[11..8]**. Then all the 512 patterns from all RAM buffers (with the exception of bits [31..30]) will be sent out without conversion to the GMT receiver. The input buffers on GMT receiver board are expected to be synchronized with this command.
12. Verify the content of the input buffers on GMT receiver board against expected values.

3.5. SP05 - to - MS2005 Data Transmission Test

The simplest option is to test the connection between one SP05 board and the MS2005. The most complete test would involve all 12 SP05 boards residing in the TF crate. The data is sent from the Test FIFOs on the SP05 board (main FPGA) and checked from the FIFO_C of the MS2005 and (optionally) three spy buffers on SP05 board: DAT_SF, DAT_SFE and DAT_SFM. The CCB2004 receives the clock and broadcast commands from the TTC source. Understanding of the SP05 functionality, external interfaces and internal registers is essential for this test, see [7] for details. This test also allows to measure the “safe window” (i.e. the fraction of the 80Mhz clock period within which the data from all 12 SP05 boards can be safely latched in into the M2005). The following procedures are required to run the test:

1. Program CCB2004 in the TF crate (slot 12):
 - write data = **1** into **CSRA1** (set “Discrete Logic” mode)
 - write **any data** into **CSRA3** (generate “**Soft_Reset**”)
2. Initialize the TTCrx from the TTC source as described in Section 1.1 above.

3. Program MS2005 in the TF crate (slot 14):
 - write **any data** into address **700018h** (generate “**Soft_Reset**” to the FPGA)
 - read **CSR1** (FIFO status) and make sure the returned value is **AAh** (all FIFO buffers are empty)
 - write data = **12A1h** into **CSR0** (set “Test” mode temporary for the duration of the SP initialization procedures)
 - (Optional) write data = **0** into **CSR9** (enable inputs from all SP05 boards)
 - write data = **59h** into **CSR8** (set input clock for latching data from all SP05 boards in the middle of the “safe window”)
 - write **any data** to address **70016Ah** (set “winner bit” mode).
4. Program SP05 board(s) in the TF crate (slots 6..11 and 16..21):
 - write data = **1Fh** into **ACT_XFR FA MA** (reset all FIFO buffers, all muons, all front FPGA’s)
 - write data = **1Fh** into **ACT_XFR SP MA** (reset all FIFO buffers, all muons)
 - write data = **100h** into **CSR_FCC VM MA** (set Fast Control Mode to VME)
 - write data = **00C8h** into **ACT_FCC VM MA** (reset bunch crossing counter with the command = **32h**)
 - Load Pt LUT content into **DAT_PT** (data = **0** for address = **0**)
 - (Optional) read back **DAT_PT** for verification
 - (Optional) write data = **FFFFh** into **ACT_ACR SP MA** (reset various Local/Global Phi/Eta/DT LUT address counters)
 - write data = **11FFh** into **CSR_SFC SP MA** (spy FIFO window = 512 bunch crossings)
 - write data = **39FFh** into **CSR_TFC SP MA** (will inject test patterns for 512 bunch crossings from the main FPGA on the next FC_TFRUN command, enable injecting EMU test data from DAT_TFE, enable injecting timing bits BXN0/BC0 along with data patterns)
 - (Optional) read back **CSR_TFC SP MA** for verification
 - write data = **A000h** into **CSR_SFC VM MA** (persistent mode to spy on CCB_TPSP; spy FIFO starts writing data immediately after the requested event)
 - write data = **A000h** into **CSR_TFC VM MA** (persistent mode to inject data on all events that follow; test FIFO starts injecting data immediately after the requested event).
5. Begin test iteration:
 - load 512 test patterns (2 frames each) into **DAT_TF SP M1**
 - load 512 test patterns (2 frames each) into **DAT_TF SP M2**
 - load 512 test patterns (2 frames each) into **DAT_TF SP M3**
 - load 512 test patterns (2 frames each) into **DAT_TFE SP MA**
 - (Optional) read back **CSR_TF SP** and make sure the returned value is **8400h** (Test FIFO is full)
 - write data = **0** into **CSR_FCC VM MA** (set Fast Control Mode to CCB)
 - write data = **12A0h** into **CSR0** of MS (set “Trigger” mode)
 - write data = **2** into **CSR_MWC SP MA** (enable MS interface outputs, all

SP's).

6. Send **“Start trigger”** broadcast command (=6) from the TTC source.
 7. Send **BC0** broadcast command (=1) from the TTC source.
 8. Send **“Inject data from SP”** broadcast command (=2Fh) from the TTC source.
 9. Send **“Stop trigger”** broadcast command (=7) from the TTC source.
 10. Write data = **0** into **CSR_FCC VM MA** of SP (set Fast Control Mode to VME).
 11. Write data = **12A1h** into **CSR0** of MS (return to “Test” mode).
 12. Write data = **8002h** into **CSR_MWC SP MA** (disable MS output drivers, all SP's).
 13. (Optional) Read **CSR1** from the MS2005 and verify that the **FIFO_C** is not empty (if the SP's were expecting to send valid muon patterns)
 14. (Optional) Read **CSR_TF SP** and make sure the returned value is **4000h** (test FIFO is empty).
 15. (Optional) Read **CSR_SFM SP M1/2/3** and make sure the MS spy FIFO is not empty (if the SP05 was sending valid patterns) or full (returned value = **8400h**, if all 512 patterns were valid).
 16. Read 512 words (two frames each) from **DAT_SF M[1..3]** and verify them against the data loaded into test FIFO **DAT_TF** for every muon.
 17. Read 512 words from **FIFO_C[1..4]** and compare with expected values, taking into account the number of SP05 sources in the TF crate, Pt LUT content, sorting algorithm. Note the BC0 and BXN0 bits are treated separately (see description of **DAT_TF** in the SP05 manual).
 18. Read 512 words (two frames each) from **DAT_SFE SP MA** and verify the EMU spy FIFO content against the data preloaded into EMU test FIFO **DAT_TFE SP MA**.
 19. Read 512 words (two frames each) from **DAT_SFM M[1..3]** and make sure the **MS_ID[3..1]** bits in the first frame correspond to expected results of sorting. Verify the **BXN0** and **BC0** bits according to content of the source FIFO **DAT_TFE**.
- Note: you will probably need to adjust the CSR0[15:12] bits (MS2005; delay of winner bits on MS board before they are sent to SP).**
20. Go to step 5, load another set of test patterns into **DAT_TF** and **DAT_TFE** and repeat the iteration.

To measure the “safe window”, the value loaded into the CSR8 on Step 3, should vary typically between 44h and 70h (use 44h, 45h... 70h); each step corresponds to 0.25 ns. For each step we recommend to run 300..500 iterations (up to 1000 iterations on the boundaries of the “safe window”); each iteration comprises 512 random data patterns to be loaded into every SP05. The “safe window” corresponds to error-free data transmission. Based on our experience, the average “safe window” is ~6.5 ns (**CSR8=4Ch..66h**). It is essential that all the twelve SP05 boards participate in this measurement.

3.6. How to generate the MS_L1A_Request to Track Finder backplane

Below is a sequence of steps required to generate the L1A_Request to the CCB2004 in a standalone mode (without valid inputs from Sector Processors). This procedure might be useful for debugging purposes for local triggering.

1. Write data = **11Fh** into **CSRA1** of CCB2004 (“Discrete Logic” mode)
2. Write data = **DFBCh** into **CSRB1** of CCB2004 (enable only the MS_L1A_Request source)
3. Write data = **0** to CCB2004 **base+96h** address (enable L1A counter)
4. Write data = **0** to CCB2004 **base+94h** address (reset L1A counter to 0)
5. Write data = **0** to MS2005 **base+18h** address (soft reset of MS2005)
6. Write data = **200h** to MS2005 **base+158h** address (enable MS_L1A_request in CSR0)
7. Read CCB2004 L1A counter (**base+90h** address) and make sure there is “0”
8. Write data=**FFFFh** into MS2005 **base+400h** address (Rank and Phi LUT address 0 for Muon 1)
9. Write data=**0** into MS2005 **base+400h** address (Rank and Phi LUT address 0 for Muon 1). Steps 8-9 allow to generate a single L1A_Request from the Muon Sorter. This request will also propagate to the front panel connector P4 (pins 23/24) of the CCB2004. “Muon_1” LED on the front panel of MS2005 should be flashing once).
10. Read CCB2004 L1A counter (**base+90h** address) and make sure it is = 1.

4. Data Transmission Chain Tests

The chain tests involve the following boards:

- CCB2004, MPC2004, up to 9 TMB2005 residing in the peripheral crate
- CCB2004, MS2005 and up to 12 SP05 in the Track Finder crate
- TTC source boards (for example, TTCvi/TTCvx, or TTCci) residing in the TF or separate VME crate
- (Optional) GMT receiver board residing in the GMT/GT crate

The most typical hardware configuration consists of two crates: peripheral with the CCB2004, MPC2004 and nine TMB2005 boards, and the Track Finder with the CCB2004, MS2005 and one SP05 board (Fig.2). The TTCvi and TTCvx modules are located in the TF crate. Three optical fibers connect the outputs of the MPC2004 with one triple muon input (usually, F1, the lowest part) of the SP05. The chain test may be divided into three stages:

- (1) from the TMB2005 through MPC2004 to the input FIFO on SP05;
- (2) from the input of the SP05 to output of the SP05
- (3) from the output of SP05 to the output of MS2005 (input of GMT).



Figure 2: Chain Test in the Peripheral and Track Finder crates

At a first stage of the chain test, the testing patterns are loaded into all TMB2005 boards, sent to MPC2004 and verified from the output FIFO_B buffer of MPC2004 and from input spy FIFO buffers DAT_SF FA on SP05. The steps required to perform this test are the following (see Sections 2.4 and 2.6 for more details):

1. Program and initialize the CCB2004 boards in both crates in “**Discrete Logic**” or “**FPGA External**” mode as described in Section 1.1.
2. Program and initialize the SP05 as described in Step 4, Section 2.6. Note the delay values **SFD[9:0]** in **CSR_SFC VM** and **AFD[6:0]** in **CSR_AFD FA MA** may be different from those listed in Section 2.7. Also note the bits **SFM** and **SFRT** in **CSR_SFC VM** should be “**1**” and **SFRM=0** to allow data to be captured on the next CCB_TPTMB broadcast command.
3. Program and initialize the MPC2004 board (Step 3, Section 2.5).
4. Program and initialize all TMB2005 board(s) (Steps 4-7, Section 2.5; load 255 pairs of LCT0+LCT1 into MPC RAM).
5. Send **L1Reset** broadcast command (=3h) from the TTC source to both CCB2004 boards for timing adjustments on SP05 inputs.
6. Send “**Inject patterns from TMB**” command (=24h) from the TTC source to both CCB2004 boards.
7. Read **255 words (510 frames)** from **FIFO_B[3..1]** on MPC2004 and make sure they satisfy with the sorting criteria.
8. Read **255 words (510 frames)** from **DAT_SF F1 M1/M2/M3** (for each muon) and make sure they satisfy with the sorting criteria and are equal to ones read out from **FIFO_B[3..1]** on MPC2004.
9. Read **CSR_SF** spy FIFO status and verify that the spy FIFO is empty (**SFEF=1**).
10. Read **CSR_BID** and verify that the **MPC_LINK_ID[7:0]** is equal to expected number (**MPC_ID[5:0]** as pre-programmed into the CSR0 of MPC2004 and **LINK_ID[1:0]** as hard-wired on SP05).
11. Read “**winner bits**” from participating TMB2005 boards as described in Step 12, Section 2.5.

The second stage involves the SP05 only. The testing of SP05 internal functionality is out of scope of this Guide. The third stage is described in Section 3.5. Some examples of the C++ programs to run the first and third stages of the chain test can be found in [1].

References

[1] <http://www.bonner.rice.edu/~sangjoon/CMS/EmtTests/Src/>

History

12/06/2006. Section 2.3 was added.

01/10/2007. Major additions to Sections 2 and 3.

01/19/2007. Minor additions to Section 3.5. Sections 1.2 and 1.4 were expanded, Sections 1.5 and 4 added.

02/06/2007. Appendix was added.

02/27/2007. Minor changes in Section 1.1. Section 1.6 was added.

02/21/2008. Corrections in Section 1.2

03/06/2008. Section 1.7 was added.

05/01/2008. Minor changes in Section 1.1.

10/01/2008. Minor changes in p.11 of Section 1.1.

05/11/2009. Section 3.6 was added.

08/05/2009. Corrections in Section 3.4.

10/13/2009. Section 2.5.1 was added. Minor corrections in Section 2.5.

1. Peripheral Backplane

The picture of the EMU custom peripheral 9U backplane designed at the University of Florida, Gainesville (revision 3, production version, front view) is shown on Fig.1. The upper part complies with the VME64x protocol that uses a unique geographical address for every slot 1..21. The base 24-bit addresses according to geographical addressing scheme board are listed in Table 1 for every slot. All the other connectors are female type metric (2 mm) 5- or 7-row Zpack (Example is shown on Fig.2). Pin assignment of the CCB, MPC, TMB and DMB backplane connectors is given in Tables 2-5 respectively.

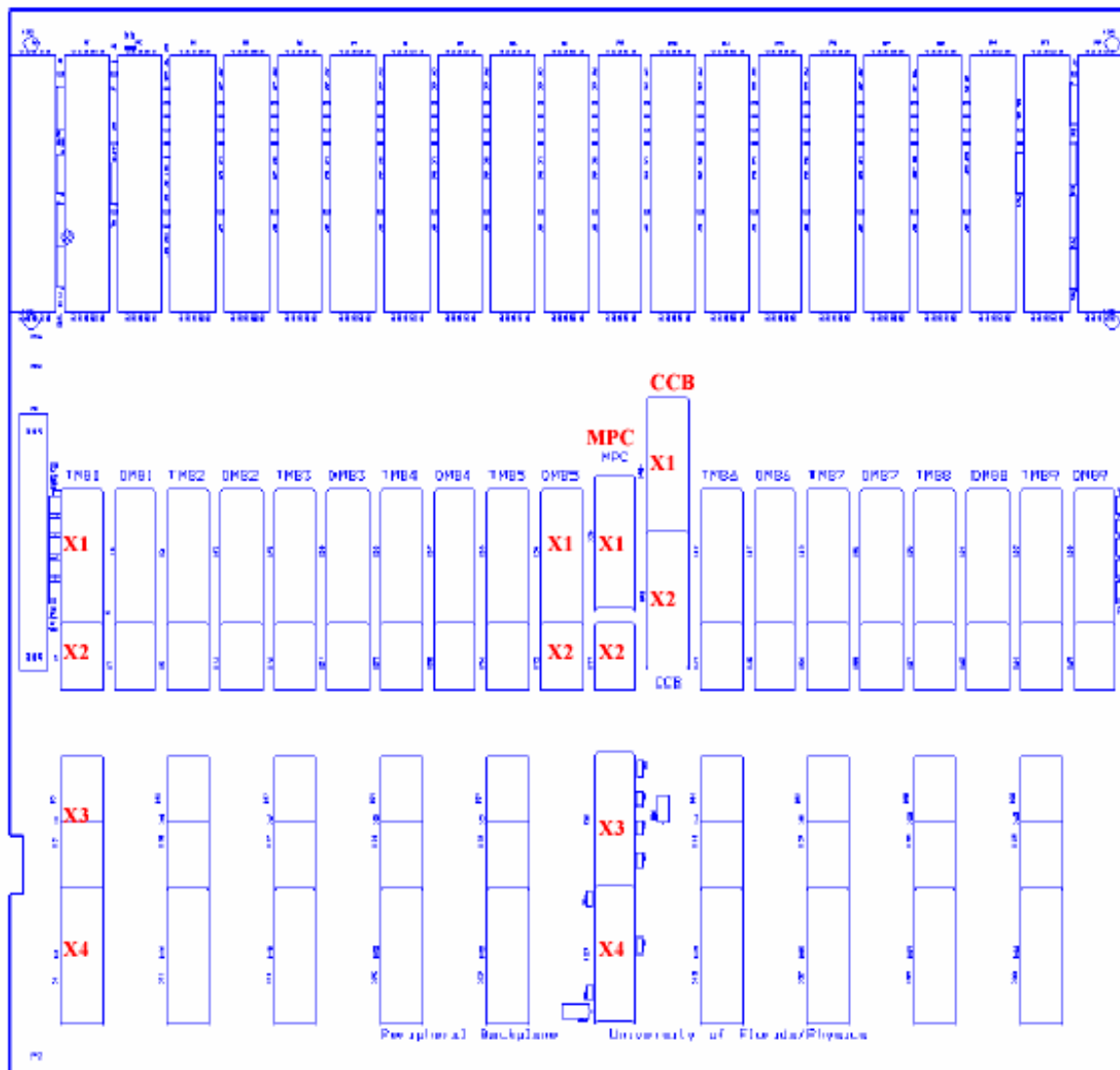


Figure 1: EMU Custom Peripheral Backplane, front view

Table 1: Geographical Addressing in the EMU Peripheral Crate

VME Slot	Board	Base Address	VME Slot	Board	Base Address	VME Slot	Board	Base Address
1	CC		8	TMB4	400000h	15	DMB6	780000h
2	TMB1	100000h	9	DMB4	480000h	16	TMB7	800000h
3	DMB1	180000h	10	TMB5	500000h	17	DMB7	880000h
4	TMB2	200000h	11	DMB5	580000h	18	TMB8	900000h
5	DMB2	280000h	12	MPC	600000h	19	DMB8	980000h
6	TMB3	300000h	13	CCB	680000h	20	TMB9	A00000h
7	DMB3	380000h	14	TMB6	700000h	21	DMB9	A80000h

Power distribution in the EMU peripheral backplane is different from standard VME backplane. Only +3.3V (as specified in the VME64x document for pins D12, D14, D16, D18, D20, D22, D24, D26, D28, D30) and +5.0V (pins A32, B32, C32) are provided. +12V and -12V powers are not provided. The power comes from the Crate Regulator Board (CRB) located behind the J1/P1 portion of the custom backplane. The CRB provides +3.3V and +5.0V powers individually to each slot in the crate. In addition, the CRB provides two sources of +1.5V required for the GTLP terminators: one for the MPC and another for all other boards (CCB, TMB1-9, DMB1-9). The +3.3V power for RAT1-9 cards comes from the corresponding TMB board (Table 4, connector 4). The CRB output voltages can be monitored over CAN bus. Some of the voltages can be monitored on a TMB2005 board accessing the ADR_ADC register. An example of the program is given in [2].

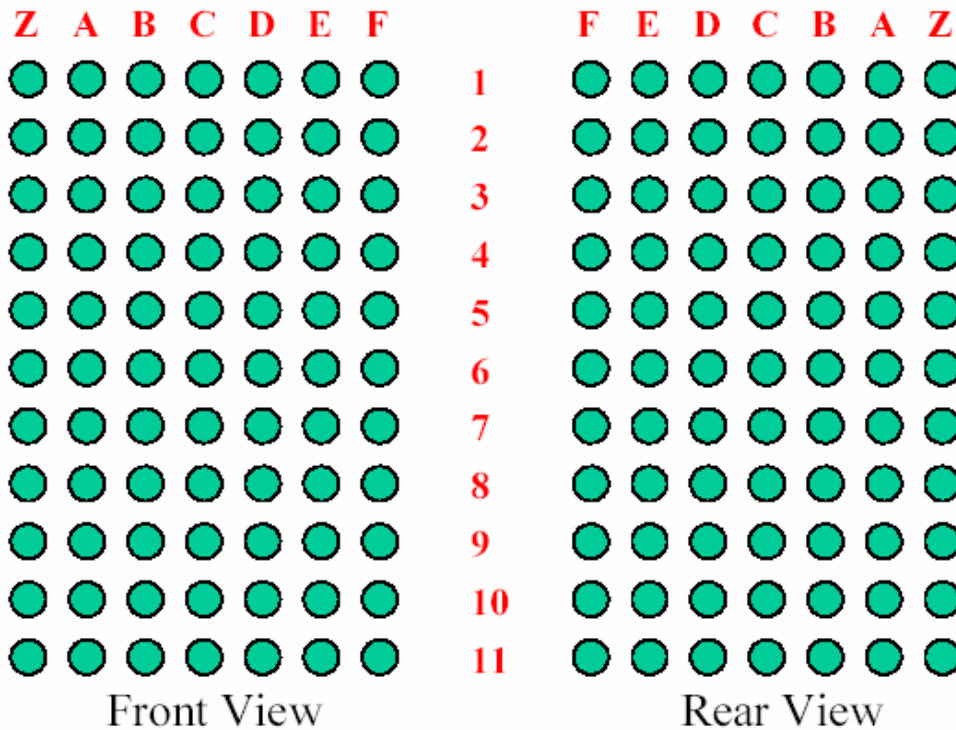
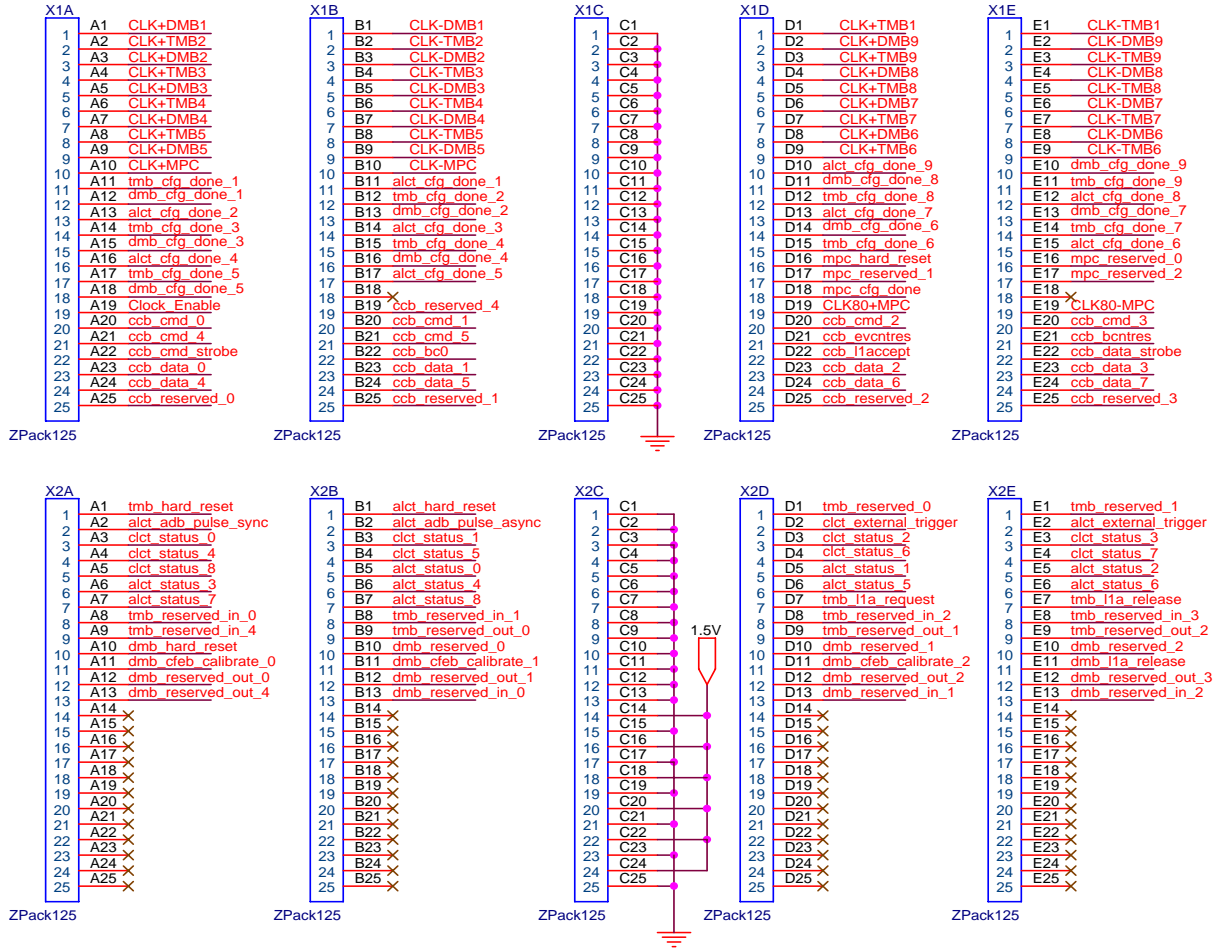


Figure 2: Pin assignment of the Zpack77 connector

Table 2: CCB Slot



All bussed GTLP signals (full list is given in Table 3A of the CCB Specification [1]) are terminated on both ends of the peripheral backplane. All 40MHz and 80MHz point-to-point signals are terminated on receiving boards: 100 Ohm to +1.5V for GTLP, 100 Ohm between the complementary signals for LVDS (40MHz and 80MHz clocks from the CCB).

Table 3: MPC Slot



Table 4: TMB Slot

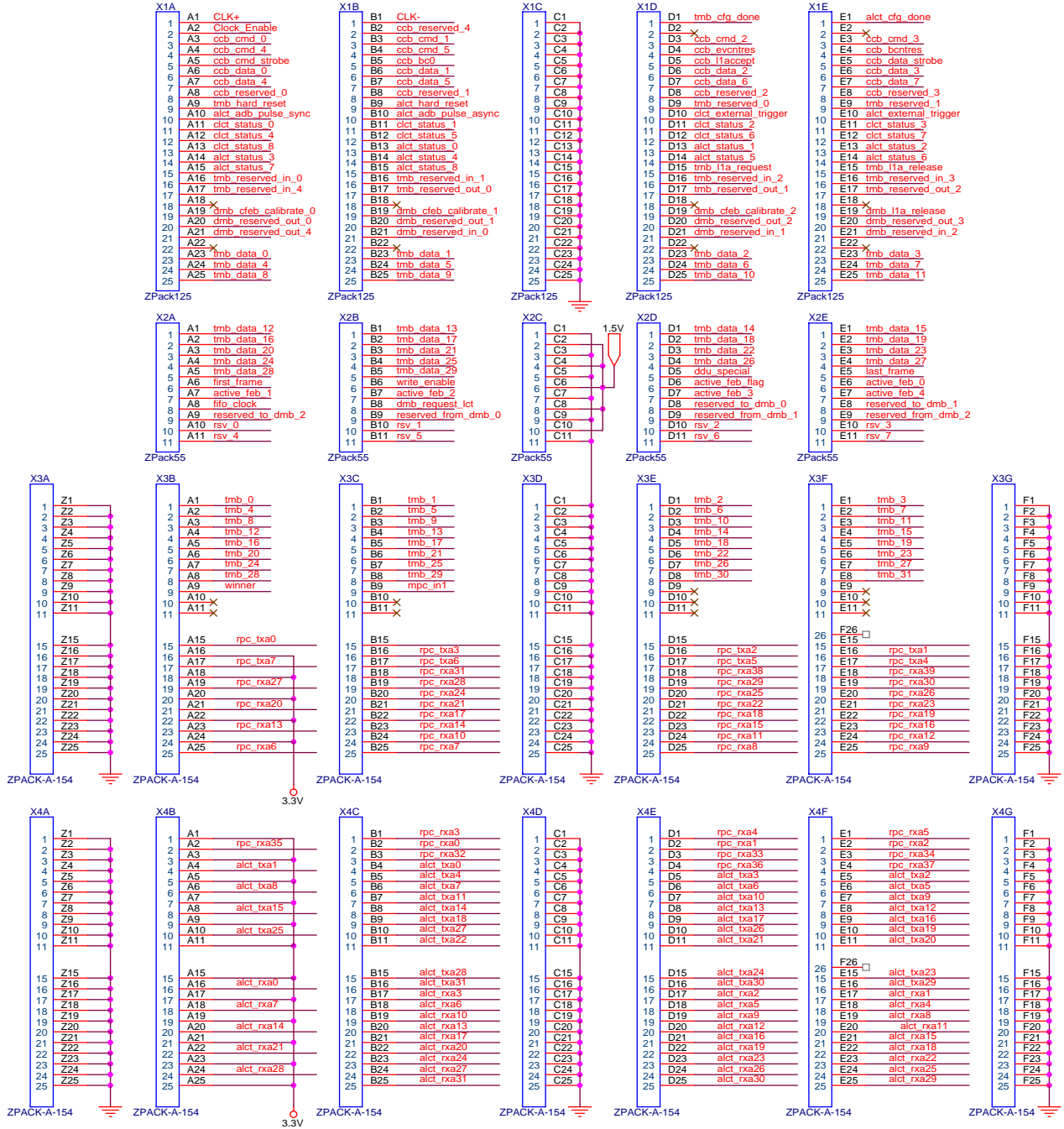
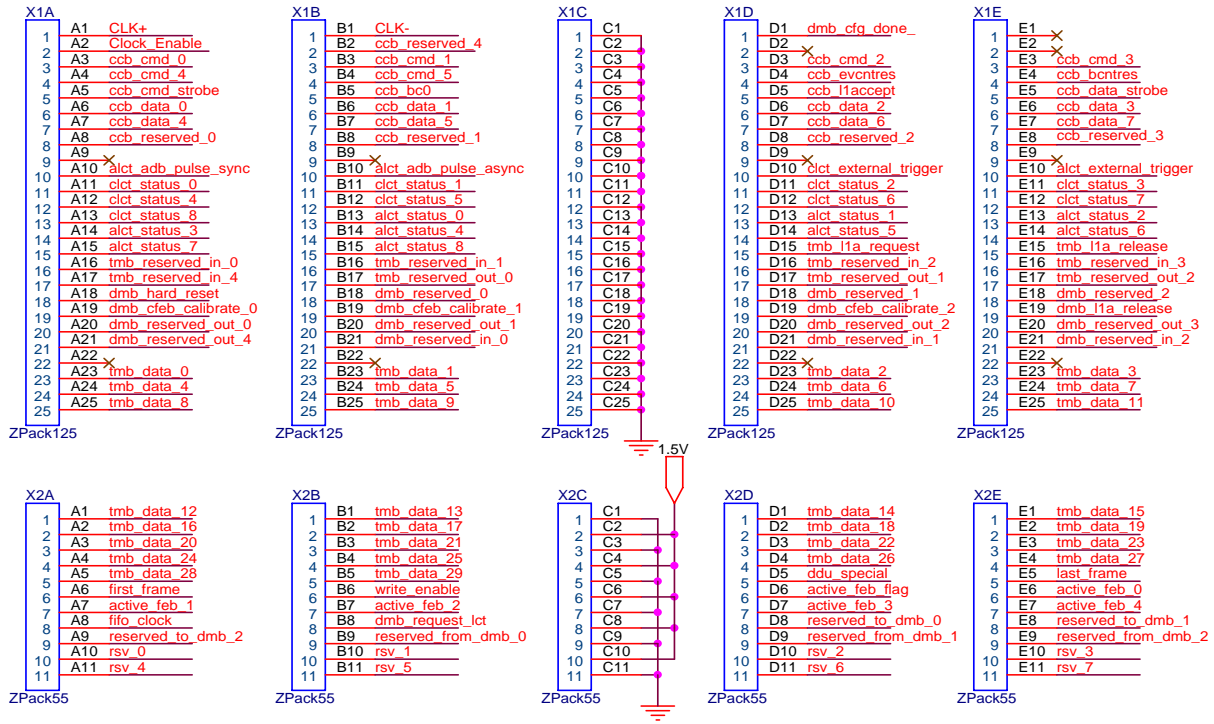


Table 5: DMB Slot



2. Track Finder Backplane

The picture of the CSC Track Finder custom 6U backplane designed at the University of Florida, Gainesville (revision 2, production version, front view) is shown on Fig.3. This backplane is located in the Track Finder (TF) crate below commercial 3U VME64x backplane which utilizes the geographical addressing scheme as described in Table 6. The TF crate is a customized Wiener 6023 [3] part with the power supply that provides the +5.0V, +3.3.V and (optionally) +12V and -12V. The Wiener power supply is connected to 3U VME64x backplane with several wires as specified by Wiener. Three thick wires for the GND, +5.0V and +3.3V are required for connection between the VME64x and custom 6U backplanes. An additional custom mezzanine card (Fig.4) available from the University of Florida should be mounted on custom backplane to provide +1.5V for the GTLP terminators. Pin assignment of all female type metric (2 mm) 5- or 7-row Zpack connectors for the CCB, MS, SP, DDU and MPC slots is shown in Tables 7-11 respectively. Note the MPC slots are implemented only partially (compare with Table 2). The MPC may only receive the CCB 40MHz and 80MHz clocks and commands. The main goal of putting the MPC into the TF crate is to provide a source(s) of data for the SP boards for testing purposes.

Table 6: Geographical Addressing in the TF Crate

VME Slot	Board	Base Address	VME Slot	Board	Base Address	VME Slot	Board	Base Address
1	CC		8	SP3	400000h	15	None	780000h
2	DDU	100000h	9	SP4	480000h	16	SP7	800000h
3	MPC1	180000h	10	SP5	500000h	17	SP8	880000h
4	MPC2	200000h	11	SP6	580000h	18	SP9	900000h
5	MPC3	280000h	12	CCB	600000h	19	SP10	980000h
6	SP1	300000h	13	None	680000h	20	SP11	A00000h
7	SP2	380000h	14	MS	700000h	21	SP12	A80000h

All bussed GTLP signals (full list is given in Table 3B of the CCB Specification [1]) are terminated on both ends of the TF custom backplane. All 40MHz and 80MHz point-to-point signals are terminated on receiving boards: 100 Ohm to +1.5V for GTLP, 100 Ohm between the complementary signals for LVDS (40MHz and 80MHz clocks from the CCB).

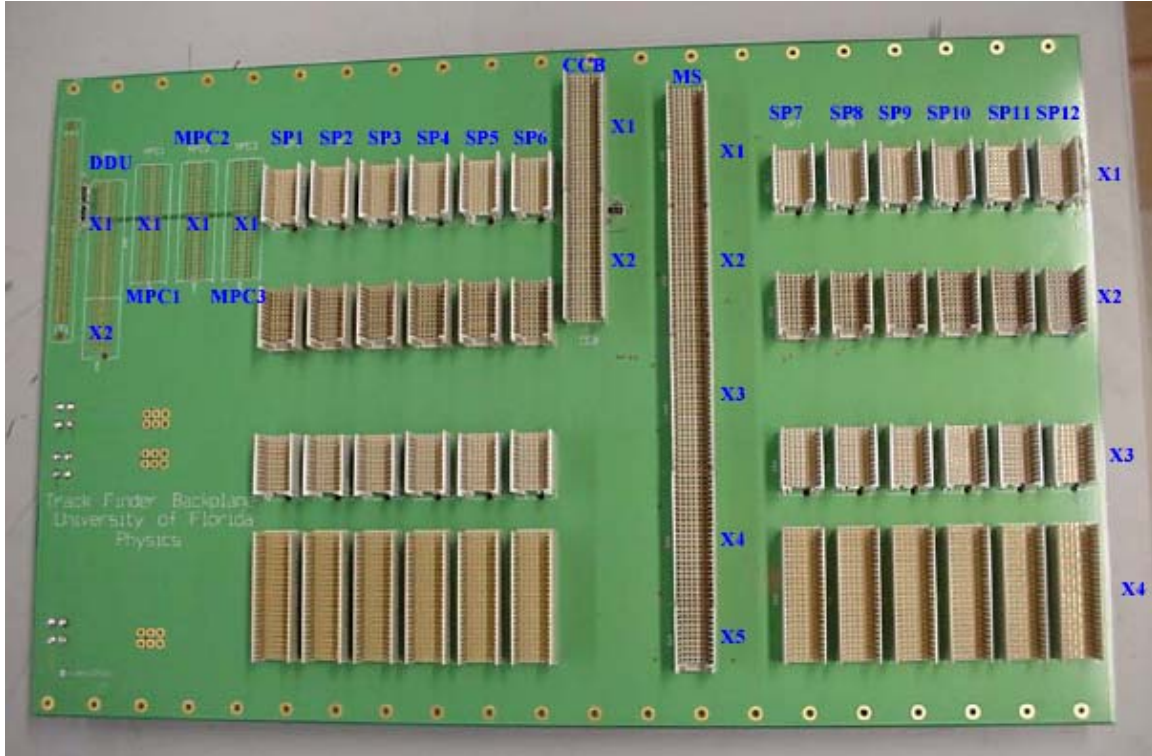


Figure 3: Track Finder custom 6U backplane, front view

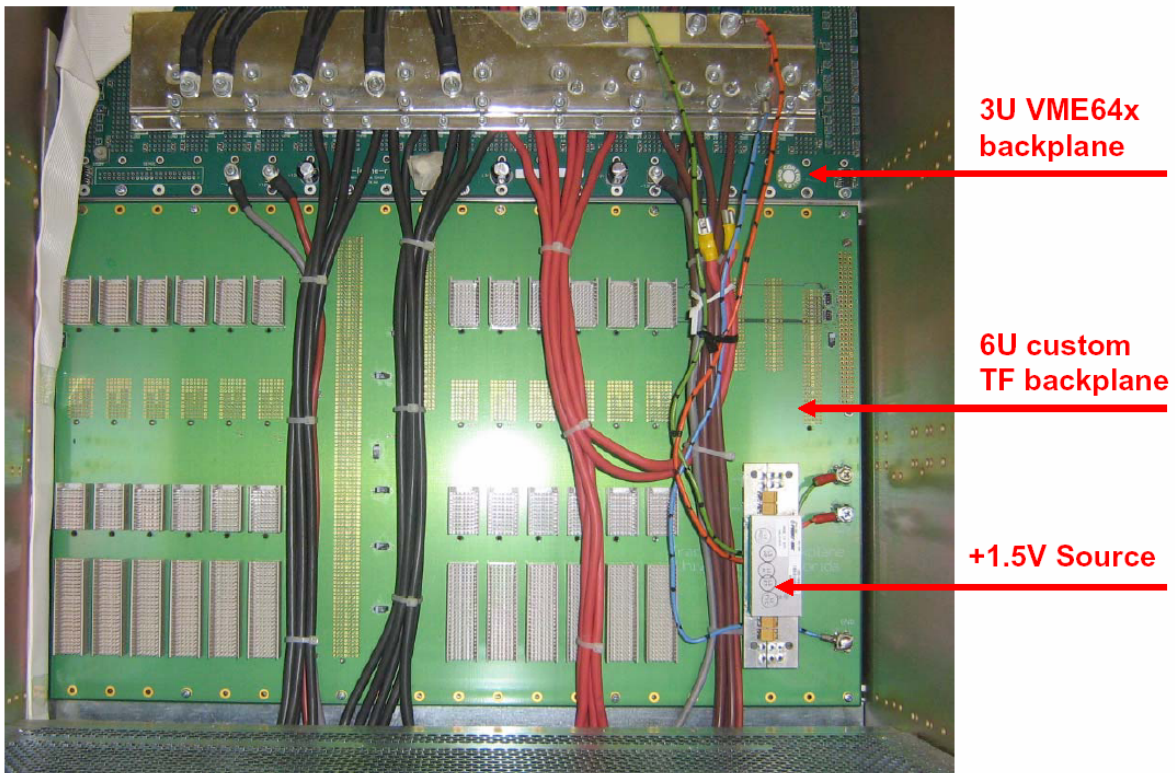


Figure 4: Track Finder crate, rear view

Table 7: CCB Slot

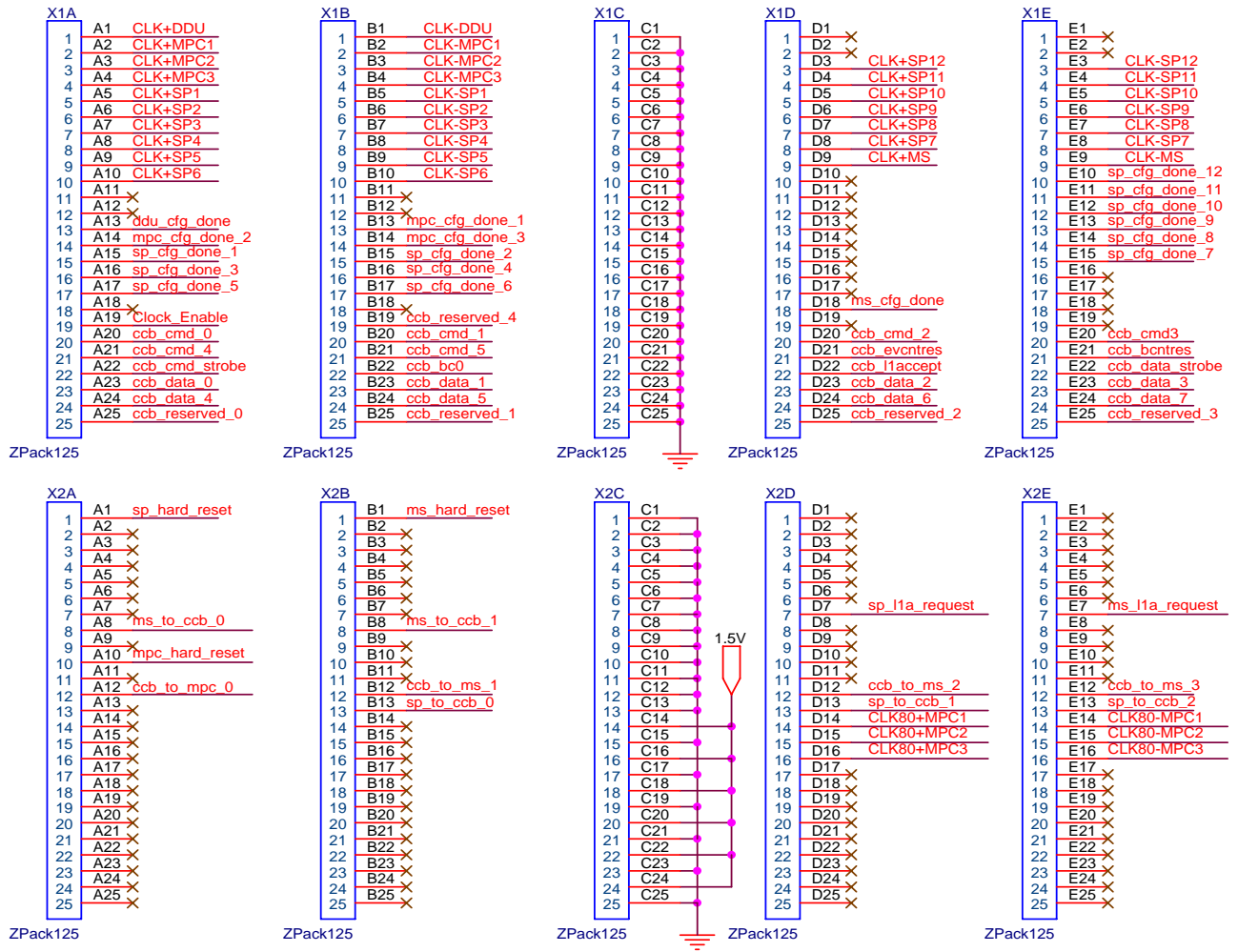


Table 8: MS Slot

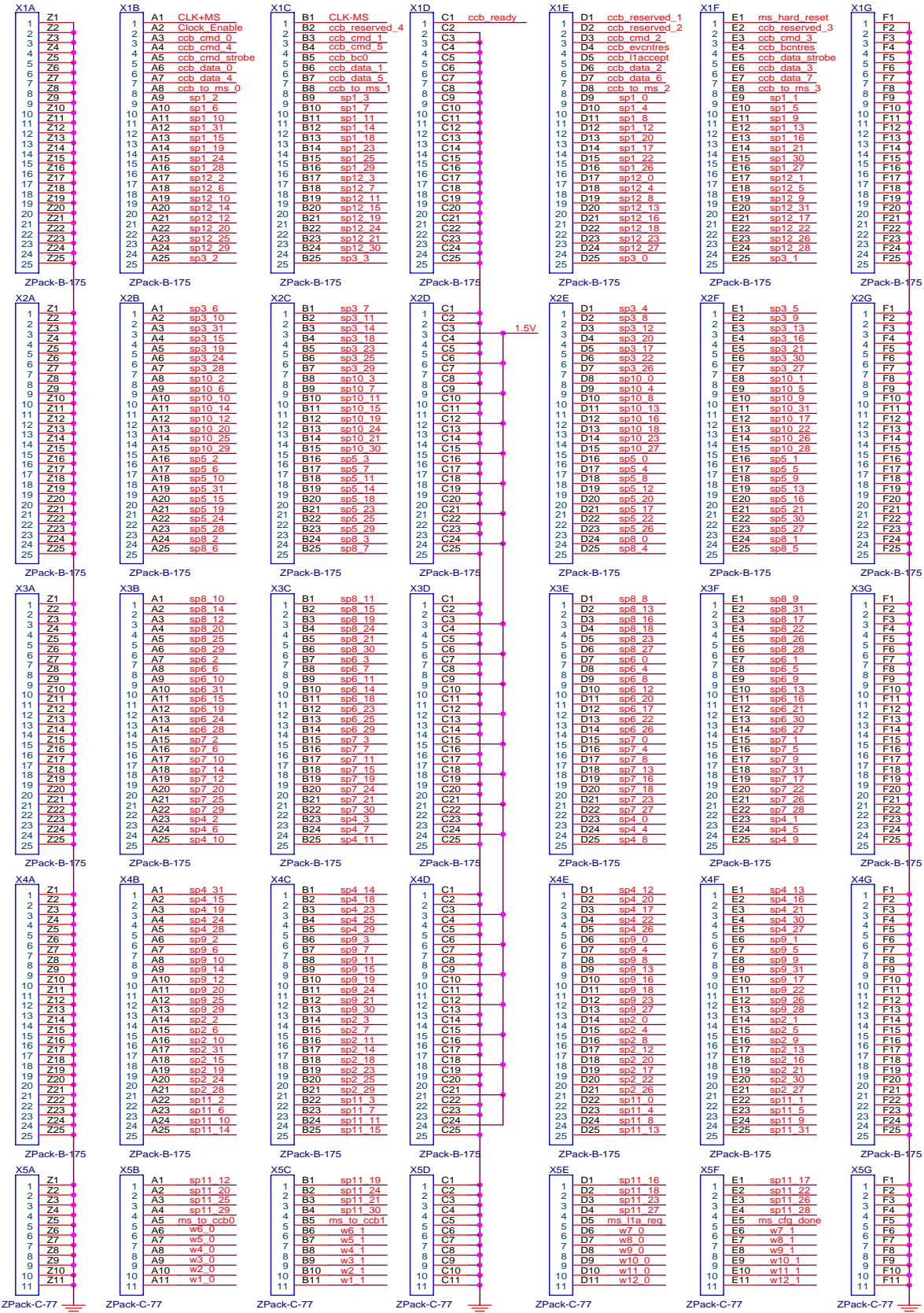


Table 9: SP Slot

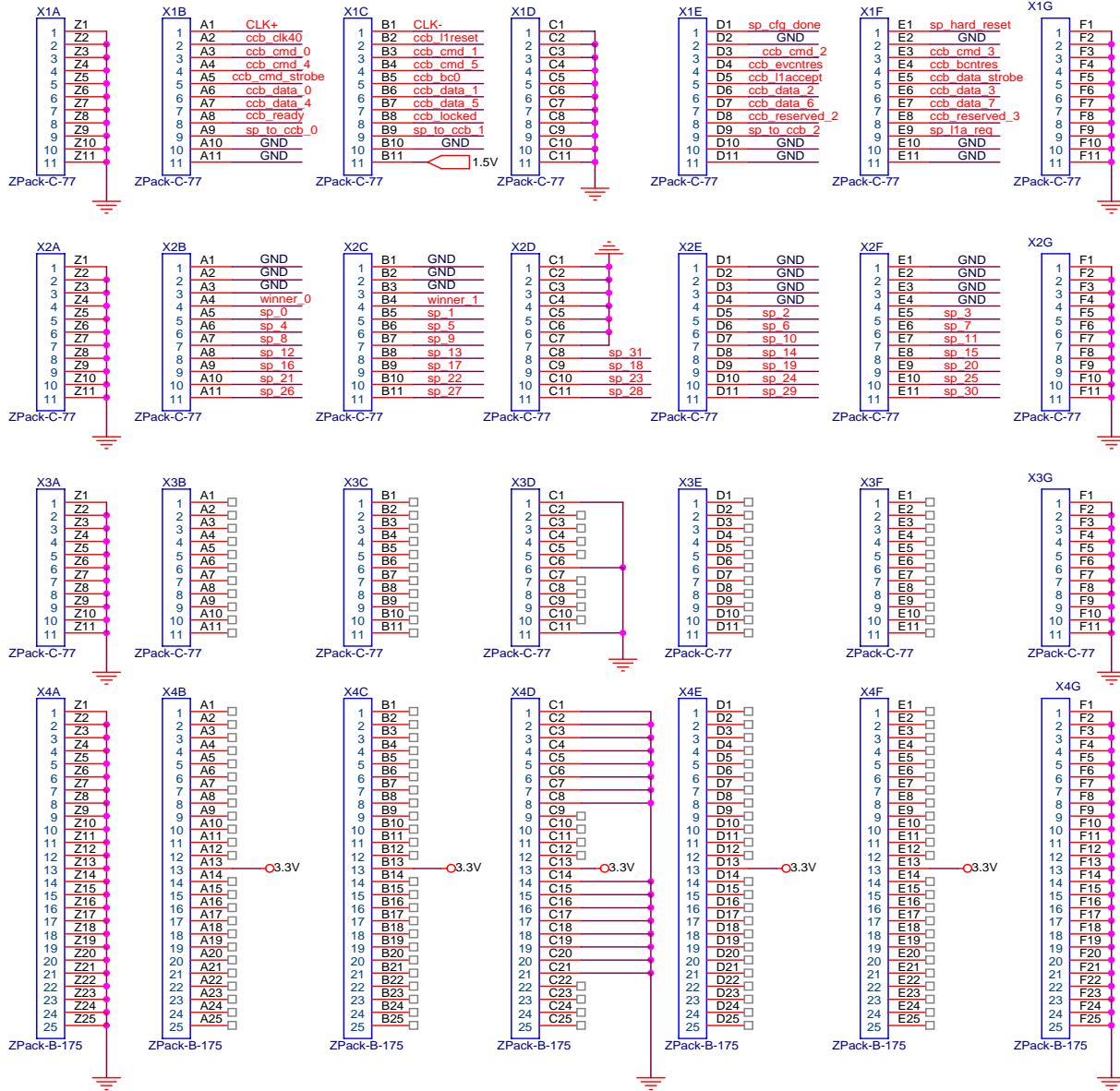


Table 10: DDU Slot

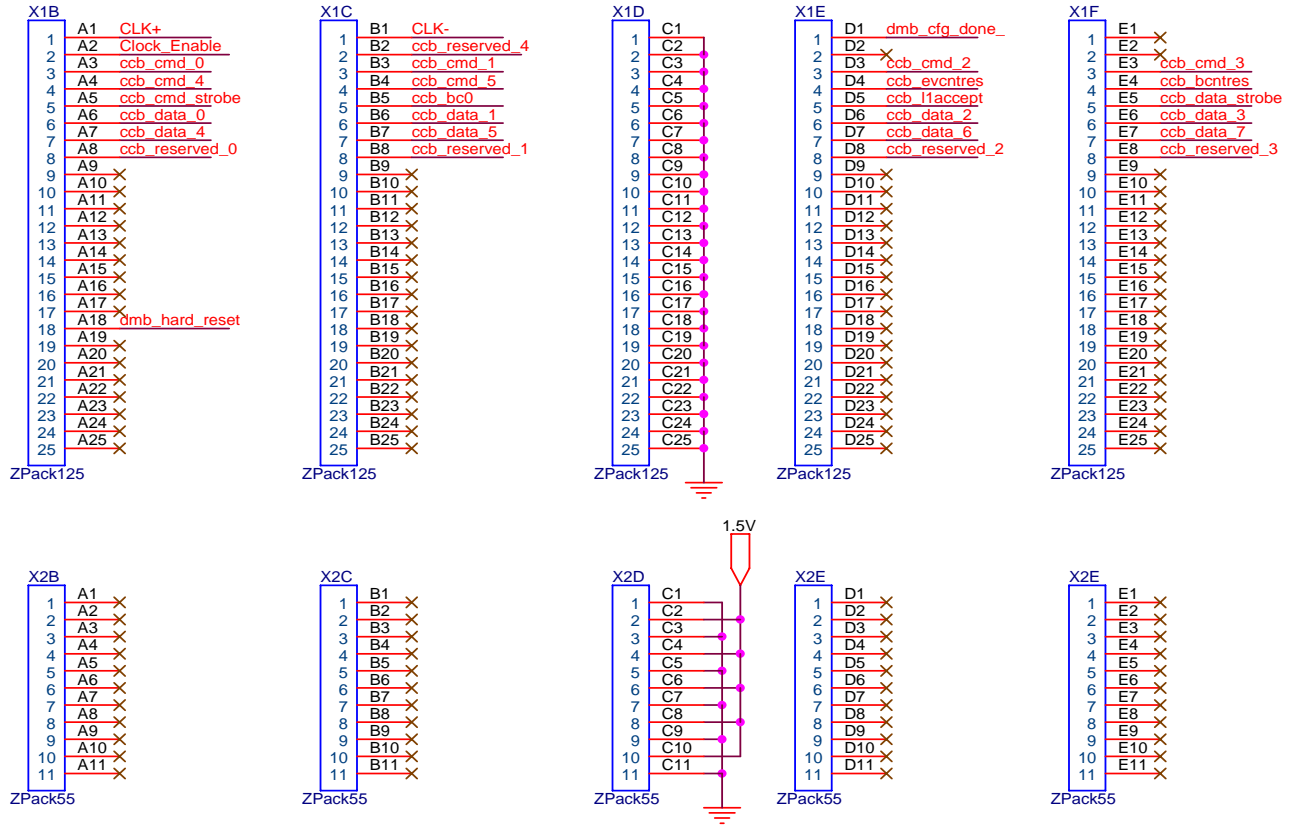
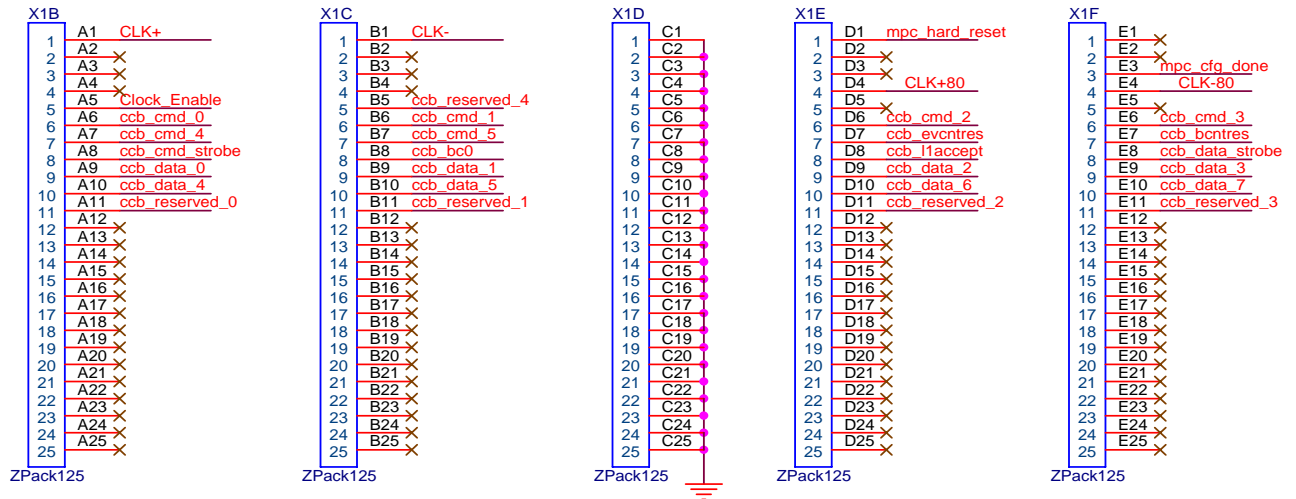


Table 11: MPC Slot



3. VME Backplanes

P1/J1 Pin Assignment					
Pin	Row Z (2)	Row A	Row B	Row C	Row D (2)
1	MPR	D00	BBSY*	D08	VPC (3)
2	GND	D01	BCLR*	D09	GND (3)
3	MCLK	D02	ACFAIL*	D10	+V1
4	GND	D03	BG0IN*	D11	+V2
5	MSD	D04	BG0OUT*	D12	RsvU
6	GND	D05	BG1IN*	D13	-V1
7	MMD	D06	BG1OUT*	D14	-V2
8	GND	D07	BG2IN*	D15	RsvU
9	MCTL	GND	BG2OUT*	GND	GAP*
10	GND	SYSCLK	BG3IN*	SYSFAIL*	GA0*
11	RESP*	GND	BG3OUT*	BERR*	GA1*
12	GND	DS1*	BR0*	SYSRESET*	+3.3V
13	RsvBus	DS0*	BR1*	LWORD*	GA2*
14	GND	WRITE*	BR2*	AM5	+3.3V
15	RsvBus	GND	BR3*	A23	GA3*
16	GND	DTACK*	AM0	A22	+3.3V
17	RsvBus	GND	AM1	A21	GA4*
18	GND	AS*	AM2	A20	+3.3V
19	RsvBus	GND	AM3	A19	RsvBus
20	GND	IACK*	GND	A18	+3.3V
21	RsvBus	IACKIN*	SERA (1)	A17	RsvBus
22	GND	IACKOUT*	SERB (1)	A16	+3.3V
23	RsvBus	AM4	GND	A15	RsvBus
24	GND	A07	IRQ7*	A14	+3.3V
25	RsvBus	A06	IRQ6*	A13	RsvBus
26	GND	A05	IRQ5*	A12	+3.3V
27	RsvBus	A04	IRQ4*	A11	LI/I*
28	GND	A03	IRQ3*	A10	+3.3V
29	RsvBus	A02	IRQ2*	A09	LI/O*
30	GND	A01	IRQ1*	A08	+3.3V
31	RsvBus	-12 VDC	+5VSTDBY	+12 VDC	GND (3)
32	GND	+5 VDC	+5 VDC	+5 VDC	VPC (3)

- (1) Pin(s) redefined under the VME64 specification.
(2) Pin(s) redefined under the VME64x specification
(3) Elongated (mate first, break last) connector contact.

P2/J2 Pin Assignment					
Pin	Row Z (2)	Row A	Row B	Row C	Row D (2)
1	UsrDef	UsrDef	+5 VDC	UsrDef	UsrDef (3)
2	GND	UsrDef	GND	UsrDef	UsrDef (3)
3	UsrDef	UsrDef	RETRY* (1)	UsrDef	UsrDef
4	GND	UsrDef	A24	UsrDef	UsrDef
5	UsrDef	UsrDef	A25	UsrDef	UsrDef
6	GND	UsrDef	A26	UsrDef	UsrDef
7	UsrDef	UsrDef	A27	UsrDef	UsrDef
8	GND	UsrDef	A28	UsrDef	UsrDef
9	UsrDef	UsrDef	A29	UsrDef	UsrDef
10	GND	UsrDef	A30	UsrDef	UsrDef
11	UsrDef	UsrDef	A31	UsrDef	UsrDef
12	GND	UsrDef	GND	UsrDef	UsrDef
13	UsrDef	UsrDef	+5 VDC	UsrDef	UsrDef
14	GND	UsrDef	D16	UsrDef	UsrDef
15	UsrDef	UsrDef	D17	UsrDef	UsrDef
16	GND	UsrDef	D18	UsrDef	UsrDef
17	UsrDef	UsrDef	D19	UsrDef	UsrDef
18	GND	UsrDef	D20	UsrDef	UsrDef
19	UsrDef	UsrDef	D21	UsrDef	UsrDef
20	GND	UsrDef	D22	UsrDef	UsrDef
21	UsrDef	UsrDef	D23	UsrDef	UsrDef
22	GND	UsrDef	GND	UsrDef	UsrDef
23	UsrDef	UsrDef	D24	UsrDef	UsrDef
24	GND	UsrDef	D25	UsrDef	UsrDef
25	UsrDef	UsrDef	D26	UsrDef	UsrDef
26	GND	UsrDef	D27	UsrDef	UsrDef
27	UsrDef	UsrDef	D28	UsrDef	UsrDef
28	GND	UsrDef	D29	UsrDef	UsrDef
29	UsrDef	UsrDef	D30	UsrDef	UsrDef
30	GND	UsrDef	D31	UsrDef	UsrDef
31	UsrDef	UsrDef	GND	UsrDef	GND (3)
32	GND	UsrDef	+5 VDC	UsrDef	VPC (3)

(1) Pin(s) redefined under the VME64 specification.

(2) Pin(s) redefined under the VME64x specification

(3) Elongated (mate first, break last) connector contact.

References

[1] CCB2004 Specification. http://bonner-ntserver.rice.edu/cms/CCB2004P_041205.pdf

[2] <http://bonner-ntserver.rice.edu/cms/tlc2543.txt>

[3] Wiener 9U VME 6023 Crate Series. <http://www.wiener-d.com/products/11/2.html>